LV8727E

Tiny 2.5A Bipolar Stepper Motor Driver



Applications

Tiny Board has been designed around LV8772 IC from On-Semi. This driver is capable of micro-step drive and supports 4W 1-2 phase excitation. It has Low on Resistance with motor current selectable in four steps. The board is equipped with unusual condition warning LED and input Pulse Monitor LED. It is most suitable for the drive of a stepping motor for OA, amusements, hobby CNC, 3D printers, automatic machines, linear guides, motion control systems, XY gantry, Camera focus and zoom controller, Mini camera Pan Tilt Head.

Features

Power Supply input 9V to 30V (Max 32V) Output Current 2.5Amps Very low noise and smooth operations Very low noise in slow speed Low on resistance (Total of upper and lower: 0.550hms) Micro-Step mode can be set to Full-Step, 1/2 Step, 1/4, 1/16 Steps Motor Current selectable in four steps Output short circuit protection circuit incorporated (IC) Built in thermal shutdown circuit No Control power supply required Input Signals 1. Step (Clock) 2. Direction 3. Enable 4. Reset This Drive default set to enable and reset Current Setting via onboard Preset (Potentiometer) Attenuation ATT1 and ATT2 by Jumpers Two Jumpers for Micro-Step settings **On-Board Fault Warning LED On-Board Pulse Input indication LED**

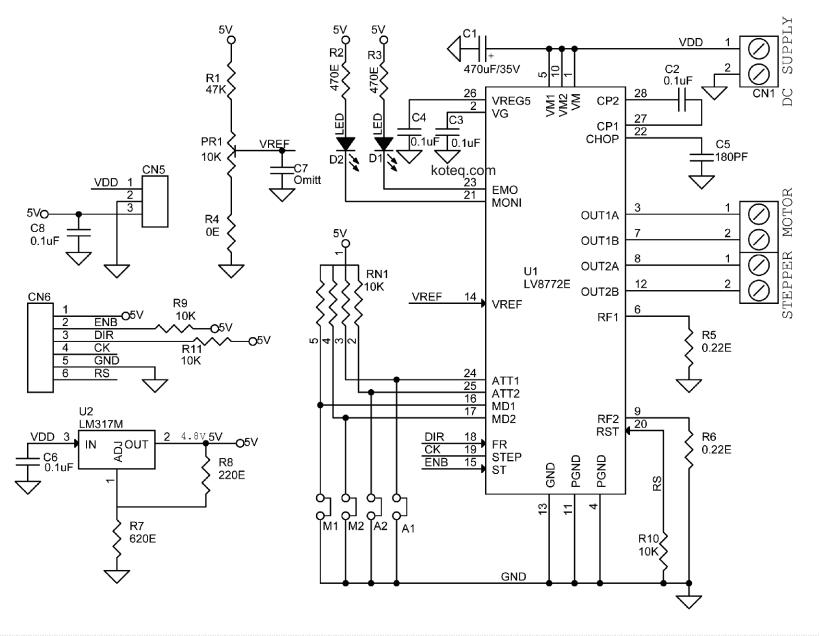
Slot Machine Vending Machine Cash Machine PPC (Plain Paper Copier) LBP (Laser Beam Printer) Scanner CNC 3D Printers Textile Camera Pan Tilt Head Camera Focus and Zoom Controller





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LV8772E BASED 2.5A TINY BIPOLAR STEPPER MOTOR DRIVER

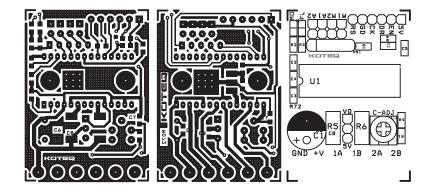
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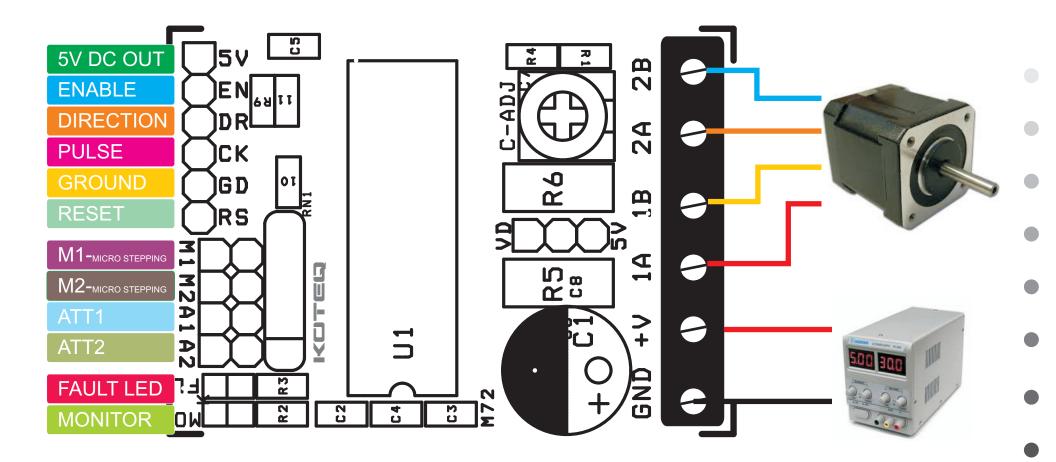


	BOM					
SR	QNTY	REF	DESCRIPTION			
1	4	M1,A1,M2,A2 2 PIN JUMPERS & CLOSE				
2	3	CN1,CN2,CN3 2 PIN SCREW TERMINAL				
3	1	CN5 3 PIN HEADER CONNECTO				
4	1	CN6 6 PIN HEADER CONNECTO				
5	1	C1 470uF/35V				
6	5	C2,C3,C4,C6,C8 0.1uF				
7	1	C5 180PF				
8	1	C7 0.1uF				
9	2	D1,D2 LED SMD 0805 RED AND GR				
10	5	RN1,PR1,R9,R10,R11 10K SMD 0805				
11	1	R1 47K SMD 0805				
12	2	R2,R3	470E SMD 0805			
13	1	R4	0E SMD 0805			
14	2	R5,R6	0.22E SMD 0805			
15	1	R7	620E SMD 0805			
16	1	R8 220E SMD 0805				
17	1	U1 LV8772E SMD 0805				
18	1	U2 LM317M SMD DPACK				
19	1	PR1 PRESET 10K				
20	1	RN1	5 PIN RESISTOR NETWORK			



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Chip Enable Functions (Default this pin set to high for normal operation)

ST Pin High Operation Mode, Low Disable the drive

This IC is switched between standby and operating mode by setting the ST pin, In standby mode, the IC is set to power-save mode and all logic is reset. In addition, the internal regulator circuit and charge pump circuit do not operate in standby mode.

Position Detection Monitoring Function (LED MO, D2)

When the excitation position is in the initial position, the Monitor output **LED MO** D2 placed in the ON State

Setting Constant-Current control reference current (PR1 Potentiometer)

Potentiometer PR1 is to set the Current

RESET Function (Default This Pin set to normal operation using pull down resistor R10)

Reset Pin **Low** = Normal Operation, Reset Pin **High** = Reset State When The RST pin is set to High, the excitation position of the output is forcibly set to the initial state, and the Moni -D2 LED is in ON state, When RST is set to low, the excitation position is advanced by the next STEP input

Output Short Circuit

Output Short-Circuit protection type of IC is latch type to turn off when the output current exceeds the detection current and the state is maintained. The output short-circuit protection circuit is activated in and event of short-circuit in the output pin. When the short-circuit state continues for a period of time set by the internal timer (approximately 4uS), the output in which short-circuit was first detected are switched to the standby mode, And if the short-circuit state is still detected, all the outputs of the channel are switched to the standby mode, and the state is held, this state is released by setting ST to low.

EMO Unusual Condition Warning Output Pin (Fault LED D1)

This board is provided with EMO (Fault LED) which notifies the CPU of an unusual condition if the protection circuit operates by detecting an unusual condition of the IC, When an unusual condition is detected , the Fault LED D1 is placed in the ON (EMO=Low)

Chopping Frequency

F-Chop 10uA/180PF/).5VX2=55Khz

Connections

CN1: Power Supply In CN2: Bipolar Stepper Motor Connections CN6: Control Signal Inputs (All inputs are TTL Level)

> Pin1 5V : DC Aux (Output) Pin 2 ENB : Enable (Default set to Enable , Required low input (Pull Down) to disable) Pin3 CK : Clock input to excite the motor (Pulse Inputs) Pin 4 : GND Ground Signal Pin5 : RS : Reset input

PR1: Onboard Preset (Potentiometer) to set the Current
D1 : Fault LED
D2 : Pulse Monitor LED
CN5 : Aux. Power Supply Output, Supply 24V, 5V Regulated, Ground
M1, M2 : Jumpers to set the Micro-stepping
A1,A2: To Set the Motor Holding Current (A1=ATT1, A2=ATT2)

MICRO-STEP SETTINGS				
SR	M1	M2	Micro-Step RESOLUTION	
1	LOW	LOW	FULL STEP	
2	HIGH	LOW	HALF STEP	
3	LOW	HIGH	QUARTER STEP	
4	HIGH	HIGH	1/16 STEP	
JUN	IPER CLOS	SED=LOW	I JUMPER OPEN= HIGH	

Current Setting Reference Voltage Attenuation Ratio (A1 & A2 Closed= Low, Open=High)

ATT1-A1 Low, ATT2-A2 Low = 100% ATT1-A1 High I ATT2-A2 Low = 80% ATT1-A1 Low I ATT2-A2 High = 50% ATT1-A1 High I ATT2-A2 High = 20%

The formula used to calculate the output current when using the function for attenuating the VREF input voltage is giving bellow

I out+(VREF/%)X(Attenuation Ratio)/RF resistance

Example: At VREF of 1.0V, a reference voltage setting of 100% (ATT1-A1=Low ATT2-A2=Low) and an RF resistance of 0.5 Ohms, the output current is set as shown bellow,

I-Out=1.0VX5X100%/0.22Ohms=0.91A

If, in this state (ATT1-A1=High, ATT2-A2=High), I-Out will be as follows:

I-Out = 0.91AX50%=455Ma

In this way, the output current is attenuated when the motor holding current is supplied so that power can be conserved.