

400 kHz, High Accuracy Current Sensor

with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

FEATURES AND BENEFITS

- High operating bandwidth for fast control loops or where high-speed currents are monitored
 - □ 400 kHz bandwidth
 - □ 2 μs typical response time
- High accuracy
 - □ 1% maximum sensitivity error over temperature (K series)
 - □ 6 mV maximum offset voltage over temperature
 - \square Non-ratiometric operation with V_{REF} output
 - □ Low noise LA package
 - \Diamond 160 mV_{RMS} for 3.3 V supply
 - \Diamond 124 mV_{RMS} for 5 V supply
 - ☐ Differential sensing for high immunity to external magnetic fields
 - □ No magnetic hysteresis
- · Adjustable fast overcurrent fault
 - □ 1 µs typical response time
 - □ Pin adjustable threshold
- Externally configurable gain settings using two logic pins
 - ☐ Four adjustable gain levels for increased design flexibility

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PACKAGE: 16-Pin SOICW (suffix MA/LA)



Not to scale

DESCRIPTION

The ACS37002 is a fully integrated Hall-effect current sensor in an SOICW-16 package that is factory-trimmed to provide high accuracy over the entire operating range without the need for customer programming. The current is sensed differentially by two Hall plates that subtract out interfering external commonmode magnetic fields.

The package construction provides high isolation by magnetically coupling the field generated by the current in the conductor to the monolithic Hall sensor IC which has no physical connection to the integrated current conductor. The MA package is optimized for higher isolation with withstand voltage, 4.8 kV $_{RMS}$, and 0.85 m Ω conductor resistance. The LA package is optimized for lower noise with 3.6 kV $_{RMS}$ withstand voltage and 1 m Ω conductor resistance.

The ACS37002 has functional features that are externally configurable and robust without the need for programming. Two logic gain selection pins can be used to configure the device to one of four defined sensitivities and corresponding current ranges. A fast overcurrent fault output provides short-circuit detection for system protection with a fault threshold that is proportional to the current range and can be set with an analog input. The reference pin provides a stable voltage that corresponds to the 0A output voltage. This reference voltage allows for differential measurements as well as a device-referred voltage to set the overcurrent fault threshold.

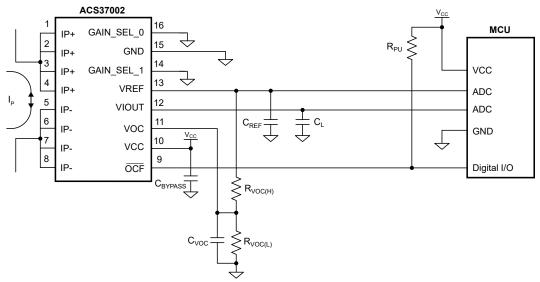


Figure 1: Typical Bidirectional Application

For more application circuits, refer to the Application and Theory section

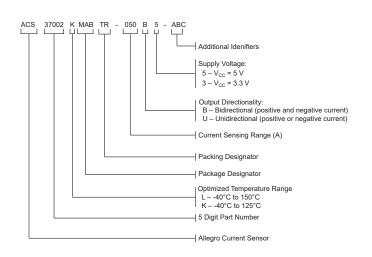
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FEATURES AND BENEFITS (continued)

- □ Enabling measurement ranges from 10 to 133 A in both unidirectional and bidirectional modes
- Low internal primary conductor resistance 0.85 m Ω (MA) and 1 m Ω (LA) for better power efficiency
- UL60950-1 (ed. 2) and UL 62368 (ed. 1) certification, highly isolated compact SOICW-16 surface mount package (MA)
 - □ 4.8 kV_{RMS} rated isolation voltage
 - $\hfill\Box$ 1097 V_{RMS} / 1550 V_{DC} basic isolation voltages
 - \Box 565 V_{RMS} / 880 V_{DC} reinforced isolation voltages
- Wide operating temperature, -40°C to 150°C
- AEC-Q100 qualified





SELECTION GUIDE

Part Number (click number to go to Performance Characteristics)	Current Sensing Range, I _{PR} (A)	Sensitivity ^[1] (mV/A)	Nominal V _{CC} (V)	Optimized Temp. Range T _A (°C)	Packing ^[2]
	MA	Package, 16-Pin SOICW			
ACS37002LMABTR-050B5	±33, ±40, ±50, ±66	60, 50, 40, 30			
ACS37002LMABTR-066B5	±66, ±80 ±100, ±133	30, 25, 20, 15	5		
ACS37002LMABTR-050U5	33, 40, 50, 66	120, 100, 80, 60	5		
ACS37002LMABTR-066U5	66, 80, 100, 133	60, 50, 40, 30		-40 to 150	
ACS37002LMABTR-050B3	±33, ±40, ±50, ±66	39.6, 33, 26.4, 19.8		-40 to 150	1000 pieces
ACS37002LMABTR-066B3	±66, ±80, ±100, ±133	19.8, 16.5, 13.2, 9.9	3.3		per 13-inch reel
ACS37002LMABTR-050U3	33, 40, 50, 66	79.2, 66, 52.8, 39.6	3.3		
ACS37002LMABTR-066U3	66, 80, 100, 133	39.6, 33, 26.4, 19.8			
ACS37002KMABTR-050B5	±33, ±40, ±50, ±66	60, 50, 40, 30	5	40 to 10E [3]	
ACS37002KMABTR-050B3	±33, ±40, ±50, ±66	39.6, 33, 26.4, 19.8	3.3	-40 to 125 ^[3]	
	LA P	ackage ^[4] , 16-Pin SOICW			
ACS37002LLAATR-015B5	±10, ±12, ±15, ±20	200,166.6,133.3,100	5		
ACS37002LLAATR-025B5	±25, ±30, ±37.5, ±50	80, 66.6, 53.3, 40	5	-40 to 150	1000 pieces
ACS37002LLAATR-015B3	±10, ±12, ±15, ±20	132, 110, 88, 66	3.3	-40 (0 150	per 13-inch reel
ACS37002LLAATR-025U3	+25, +30, +37.5, +50	105.6, 88, 70.4, 52.8	3.3		

^[1] Refer to the part specific performance characteristics sections for Gain_Sel configuration.



^[2] Contact Allegro for additional options.

^[3] The device performance is optimized from –40°C to 125°C; however, the device can still operate to an ambient temperature of 150°C. The device shares the same qualifications as the L temperature devices unless otherwise stated.

^[4] Advanced information. LA package variation is not yet released.

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ABSOLUTE MAXIMUM RATINGS

Characteristic	Symbol	Notes	Rating	Unit
Forward Supply Voltage	V _{cc}		6.5	V
Reverse Supply Voltage	V _{RCC}		-0.5	V
Forward Output Voltage	V _{FIOUT}	Applies to V_{IOUT} , V_{OCF} , and V_{REF}	$(V_{CC} + 0.7) \le 6.5$	V
Reverse Output Voltage	V _{RIOUT}	Applies to V _{IOUT} , V _{OCF} , and V _{REF}	-0.5	V
Forward Input Voltage	V _{OI}	Applies to GAIN_SEL0, GAIN_SEL1, and VOC	$(V_{CC} + 0.7) \le 6.5$	V
Reverse Input Voltage	V _{RI}	Applies to GAIN_SEL0, GAIN_SEL1, and VOC	-0.5	٧
Operating Ambient Temperature	T _A		-40 to 150	ů
Storage Temperature	T _{stg}		-65 to 165	°C
Maximum Junction Temperature	T _{J(max)}		165	°C

ISOLATION CHARACTERISTICS

Characteristic	Symbol	Notes	Rating	Unit
Dielectric Surge Voltage	V _{SURGE}	Tested ±5 pulses at 2/minute in compliance to IEC 61000-4-5 1.2 µs (rise) / 50 µs (width)	10	kV
Surge Current [1]	I _{SURGE}	Tested in compliance to IEC 61000-4-5 8 µs (rise) / 20 µs (width)	13	kA
Comparative Track Index	CTI	Material Group II	400 to 599	V

^[1] Certification pending.

MA PACKAGE SPECIFIC PERFORMANCE

Characteristic	Symbol	Notes	Rating	Unit
Distance Through Insulation	DTI	Minimum internal distance through insulation		μm
Dielectric Strength Test Voltage	V _{ISO}	Agency type-tested for 60 seconds per UL 60950-1 (edition 2) and 62368-1 (edition 1). Production tested at 3125 V _{RMS} for 1 second in accordance with UL 60950-1 (edition 2) and 62368-1 (edition 1)		V _{RMS}
Working Voltage for Basic Isolation	Maximum approved working voltage for basic (single) isolation		1550	V _{PK or} V _{DC}
Working Voltage for Basic Isolation	V_{WVBI}	according toUL 60950-1 (edition 2) and 62368-1 (edition 1)	1097	V _{RMS}
Working Voltage for Reinforced	\/	Maximum approved working voltage for reinforced isolation	800	V _{PK or} V _{DC}
Isolation	V_{WVRI}	according to UL 60950-1 (edition 2) and 62368-1 (edition 1)	565	V _{RMS}
Clearance	D _{cl}	Minimum distance through air from IP leads to signal leads		mm
Creepage	D _{cr}	Minimum distance along package body from IP leads to signal leads	7.9	mm

LA PACKAGE SPECIFIC PERFORMANCE

Characteristic	Symbol	ymbol Notes		Unit
Distance Through Insulation	DTI	Minimum internal distance through insulation	45	μm
Dielectric Strength Test Voltage	V _{ISO}	Agency type-tested for 60 seconds per UL 60950-1 (edition 2). Production tested at 3000 V _{RMS} for 1 second in accordance with UL 60950-1	3600	V _{RMS}
Working Voltage for Basic Isolation [1] V _{WVRI} Maximum ap		Maximum approved working voltage for basic (single) isolation	870	V _{PK or} V _{DC}
Working Voltage for Basic Isolation (1)	V_{WVBI}	according to UL 60950-1 (edition 2)	616	V _{RMS}
Clearance [1]	D _{cl}	Minimum distance through air from IP leads to signal leads	7.5	mm
Creepage [1]	D _{cr}	Minimum distance along package body from IP leads to signal leads	7.5	mm

^[1] Certification pending.



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PINOUT DIAGRAM AND TERMINAL LIST TABLE

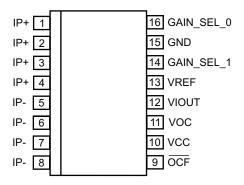


Figure 2: MA/LA Pinout Diagram

Terminal List Table

Number	Name	Description
1, 2, 3, 4	IP+	Terminals for current being sensed; fused internally
5, 6, 7, 8	IP-	Terminals for current being sensed; fused internally
9	OCF	Overcurrent fault, open-drain
10	VCC	Device power supply terminal
11	VOC	Overcurrent fault operation point input
12	VIOUT	Analog output representing the current flowing through I _P
13	VREF	Zero current voltage reference
14	GAIN_SEL_1	Gain selection bit 1
15	GND	Device ground terminal
16	GAIN_SEL_0	Gain selection bit 0

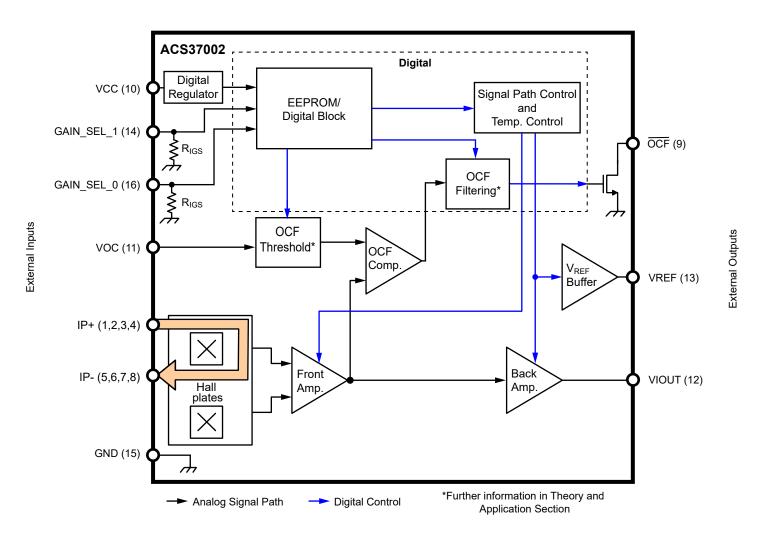


Figure 3: Functional Block Diagram

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

COMMON ELECTRICAL CHARACTERISTICS: Valid through full operating temperature range, $T_A = -40^{\circ}\text{C}$ to 150°C, $C_{\text{BYPASS}} = 0.1~\mu\text{F}$, and $V_{\text{CC}} = 5~\text{V}$ or 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions		Тур.	Max.	Units
Cumply Voltage	\/	5 V devices only	4.5	5	5.5	V
Supply Voltage	V_{CC}	3.3 V devices only	3.15	3.3	3.6	V
Cumply Current		No load on VIOUT or VREF; V _{CC} = 5 V	-	13	18	mA
ipply Current I _{CC} No		No load on VIOUT or VREF; V _{CC} = 3.3 V	-	12	15	mA
Supply Bypass Capacitor	C _{BYPASS}	VCC to GND recommended	0.1	-	_	μF
Output Resistive Load	R _L	VIOUT to GND, VIOUT to VCC	10	-	-	kΩ
Output Capacitive Load	C _L	VIOUT to GND	_	1	6	nF
Reference Resistive Load	R _{VREF}	VREF to GND (recommended to supply VOC); VREF to VCC	10	62.7	-	kΩ
Reference Capacitive Load	C _{VREF}	VREF to GND	_	-	6	nF
Fault Pull-Up Resistance	R _{PU}		4.7	-	500	kΩ
VOC Capacitive Load	C _{VOC}	VOC to GND	_	_	1	nF
Duimanus Canadusatan Daniatanaa	R _{IP}	MA,T _A = 25°C		0.85	_	mΩ
Primary Conductor Resistance		LA,T _A = 25°C	_	1	-	mΩ
Primary Conductor Inductance	L _{IP}			4.2	_	nH
Dawan On Danat Valtana	V _{POR(H)}	V _{CC} rising [1]		2.9	3.1	V
Power-On Reser vollage		V _{CC} falling [1]		2.5	2.8	V
POR Hysteresis	V _{POR(HYS)}		250	-	_	mV
Power-On Time	t _{POD}	Time from V _{CC} rising ≥ V _{UVD(DIS)} after a POR event until power-on; VREF, OCF, VIOUT	100	_	_	μs
Undervoltage Detection	$V_{\text{UVD(L)}}$	V _{CC} falling [1]	3.8	-	4.3	V
(UVD) Threshold [2]	V _{UVD(H)}	V _{CC} rising [1]	4	-	4.5	V
UVD Hysteresis [2]	V _{UVD(HYS)}		_	250	_	mV
LIVD Dolov Time [2]	t _{dUVD(E)}	Time from V _{CC} falling ≤ V _{UVD(EN)} until UVD asserts	35	64	120	μs
UVD Delay Time [2]	t _{dUVD(D)}	Time from V _{CC} rising ≥ V _{UVD(DIS)} until UVD clears	_	7	_	μs
Overvoltage Detection (OVD)	V _{OVD(H)}	V _{CC} rising ^[1]	6.1	6.3	6.8	V
Threshold	V _{OVD(L)}	V _{CC} falling [1]	5.6	5.8	6.1	V
Overvoltage Detection Hysteresis	V _{OVD(HYS)}		_	660	_	mV
OVD Dolov Timo	t _{dOVD(E)}	Time from V _{CC} rising ≥ V _{OVD(EN)} until OVD asserts	35	90	120	μs
OVD Delay Time	t _{dOVD(D)}	Time from V _{CC} falling ≤ V _{OVD(DIS)} until OVD clears	_	7	_	μs

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COMMON PERFORMANCE CHARACTERISTICS (VIOUT): Valid through full operating temperature range,

 $T_A = -40$ °C to 150°C, $C_{BYPASS} = 0.1 \mu F$, and $V_{CC} = 5 \text{ V}$ or 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	3	Min.	Тур.	Max.	Units
OUTPUT SIGNAL CHARACT	TERISTICS	(V _{IOUT})	,				
Catamatian Valtana	V _{SAT(H)}	R_L = 10 kΩ to GND		V _{CC} - 0.25	_	_	V
Saturation Voltage	V _{SAT(L)}	R_L = 10 kΩ to V_{CC}		_	_	0.15	V
		5 V linear operating range		0.5	_	4.5	V
Output Operating Range	V _{OOR}	3.3 V linear operating range		0.3	_	3.0	V
Output Current Limit	I _{OUT(src)}	/ _{IOUT} shorted to GND		-	25	_	mA
Output Current Limit	I _{OUT(snk)}	V _{IOUT} shorted to V _{CC}		_	25	_	mA
Output Drive	I _{OUT}			4.8	_	_	mA
Internal Bandwidth	BW	Small signal –3 dB, C _L = 5.7 nF		_	400	_	kHz
Rise Time	t _R	$T_A = 25$ °C, $C_L = 5.7$ nF, 10%-90% of 1 \	output swing	_	0.7	2.5	μs
Response Time	t _{RESPONSE}	$T_A = 25$ °C, $C_L = 5.7$ nF, 90% input to 90	% of 1 V output swing	_	1.1	2.5	μs
Propagation Delay	t _{pd}	$T_A = 25$ °C, $C_L = 5.7$ nF, 20% input to 20	% of 1 V output swing	_	0.7	2	μs
Noise Density	I _{ND}	Input-referenced noise density;	MA Package	_	350	_	μΑ/√Hz
		$T_A = 25$ °C, $C_L = 5.7$ nF; $V_{CC} = 5$ V	LA Package	_	155	_	μΑ/√Hz
		Input-referenced noise density; $T_A = 25^{\circ}C$, $C_L = 5.7$ nF; $V_{CC} = 3.3$ V	MA Package	_	450	_	μΑ/√Hz
			LA Package	_	200	_	μΑ/√Hz
		Imput referenced fields at 400 Kirz,	MA Package	_	277	_	mA _{RMS}
Noise			LA Package	_	124	_	mA _{RMS}
NOISE	I _N	Input-referenced noise at 400 kHz; MA Package	_	357	_	mA _{RMS}	
		$T_A = 25^{\circ}C, C_L = 5.7 \text{ nF}; V_{CC} = 3.3 \text{ V}$	LA Package	_	160	_	mA _{RMS}
Nonlinearity	E _{LIN}			_	±0.75	_	%
Power Supply Rejection Ratio	DCCD	DC to 1 kHz, 100 mV pk-pk ripple arour change in V _{OE}	and $V_{CC} = 5 \text{ V}, I_{P} = 0 \text{ A},$	-	-40	_	dB
Offset	PSSR _(O)	1 to 100 kHz, 100 mV pk-pk ripple aroun change in V _{OE}	ad $V_{CC} = 5 \text{ V}, I_{P} = 0 \text{ A},$	_	-30	_	dB
Power Supply Rejection Ratio	DOOD	DC to 1 kHz, 100 mV pk-pk ripple around $V_{CC} = 5 \text{ V}$, $I_P = I_{PR(MAX)}$, change in Sens		_	-15	_	dB
Sens	PSSR _(S)	1 to 100 kHz, 100 mV pk-pk ripple aroun I _P = I _{PR(MAX)} , change in Sens	ad $V_{CC} = 5 V$,	_	-6	_	dB
Power Supply Offset Error	V _{OE(PS)}	V _{CC} @ V _{CC(MIN)} or V _{CC(MAX)}		-10	_	10	mV
Power Supply Sensitivity Error	E _{SENS(PS)}	V _{CC} @ V _{CC(MIN)} or V _{CC(MAX)}		-1.5	_	1.5	%
Common-Mode Field Rejection	CMFR	Input-referred error due to common-mo	de field	_	4	_	mA/G

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COMMON PERFORMANCE CHARACTERISTICS (VREF, FAULT, GAIN_SEL): Valid through full operating temperature range, $T_A = -40$ °C to 150°C, $C_{BYPASS} = 0.1 \ \mu F$, and $V_{CC} = 5 \ V$ or 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units
REFERENCE OUTPUT CHAR	ACTERISTIC	CS (VREF)		•		
7 0 10 1		Bidirectional; V _{CC} = 5 V		2.5	2.51	V
	V _{REF(BI)}	Bidirectional; V _{CC} = 3.3 V	1.64	1.65	1.66	V
Zero Current Reference Voltage		Unidirectional; V _{CC} = 5 V	0.49	0.5	0.51	V
	V _{REF(UNI)}	Unidirectional; V _{CC} = 3.3 V	0.32	0.33	0.34	V
Defending Commont Limit	I _{REF(SRC)}	Maximum current V _{REF} can passively source	_	25	_	mA
Reference Source Current Limit	I _{REF(SNK)}	Maximum current V _{REF} can passively sink	_	-25	_	mA
Reference Slew Rate	SR _{REF}	$C_{VREF} = 0 \text{ nF, } R_{VREF} = 0 \Omega$	0.8	-	_	V/µs
OVERCURRENT FAULT CH	ARACTERIS	STICS (OCF)				
OCF On Voltage [4]	V _{FAULT-ON}	R_{PU} = 4.7 kΩ, under fault condition	_	0.07	0.4	V
OCF Sink Current [4]	I _{OCF(SNK)}	No Fault	_	100	_	nA
OCF SINK Current (*)		Fault Assertion	0.01	-	1.1	mA
\(\(\) \(\	V _{voc}	V _{CC} = 5 V	0.5	_	2	V
VOC Operating Voltage Range		V _{CC} = 3.3 V	0.33	_	1.32	V
Fault Error	E _{OCF}		-10	±3	10	%I _{OCF-OP}
OCE Unatarasia		V _{CC} = 5 V	-	6	_	%FS
OCF Hysteresis	I _{OCF(HYS)}	V _{CC} = 3.3 V	_	9	_	%FS
OCF Reaction Time [4]	t _{OCF-R}	Time from I _{OCF-OP} , with a 1.2 × I _{OCF-OP} until fault asserts	_	1	1.5	μs
OCF Mask [4]	t _{OCF-MASK}	Time I _{OCF-OP} must be present after t _{OCF-R} for fault assertion [3]	0	0	3	μs
OCF Response Time [4]	t _{OCF}	t _{OCF-MASK} = 0.5μs	_	1	1.5	μs
OCF Hold Time [4]	t _{OCF-HOLD}	Minimum duration of FAULT assertion [3]	0	0	5	ms
GAIN SELECTION PIN CHA	RACTERIST	TICS (GAIN_SEL0, GAIN_SEL1)				
Gain Select Internal Resistor	R _{GSint}		-	1	_	ΜΩ
		V _{CC} = 5 V	3.75	-	_	V
GAIN_SEL Logic Input Voltage	V _{H(SEL)}	V _{CC} = 3.3 V	2.25	-	_	V
	V _{L(SEL)}		_	-	0.5	V
Leakage Current [4]	I _{SEL(SNK)}		_	_	±10	μΑ

^[1] V_{CC} rate +1 V/ms, for best accuracy. [2] Only enabled on 5V devices.



^[3] Typical value is factory default.

^[4] Guaranteed by design and bench validated

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ACS37002LMABTR-050B5

ACS37002LMABTR-050B5 Gain, Sel Pin Performance Key

AC337002EWADTK-030D3	Ociection identifier			
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	40	50
Selection	0	1	50	40
Combination	1	0	60	33.3
	1	1	30	66.7

 $\textbf{ACS37002LMABTR-050B5 PERFORMANCE CHARACTERISTICS:} \ \ \text{Valid through full operating temperature range,} \ \ T_{A} = -40 ^{\circ}\text{C} \ \ \text{to} \ \ 150 ^{\circ}\text{C},$ C_{BYPASS} = 0.1 $\mu F,$ and V_{CC} = 5 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE	·		· ·			
		Gain Sel 00	-50	_	50	А
0 10 : 5		Gain Sel 01	-40	-	40	А
Current Sensing Range	I _{PR}	Gain Sel 10	-33.3	-	33.3	А
		Gain Sel 11	-66.7	_	66.7	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	40	-	mV/A
Compitituit.	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	50	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	60	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	-	30	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	$V_{IOUT(Q)}$	Bidirectional; I _P = 0 A, T _A = 25°C	-	2.5	-	V
TOTAL ERROR ($V_{IOUT(ACTUAL)}$ – (Sens _{(IDE} AND TOTAL ERROR COMPONENTS	AL) × I _{PR} + V _{REF})) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 150°C or -40°C to 25°C	-1.5	-0.5 ±0.6	1.5	%
7 0 101 5	V_{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
O#	.,	V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	−1 ±4	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
QVO Error		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	−3 ±5	10	mV
QVO Elloi	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT_LTD}	$I_P = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	$I_P = I_{PR(max)}, T_A = 25^{\circ}C \text{ to } 150^{\circ}C \text{ or } -40^{\circ}C \text{ to } 25^{\circ}C$	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including	V	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	$V_{REFactual} - V_{REFideal}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-2 ±3	10	mV
Offset Error Including Lifetime Drift	V	V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±5	10	mV
Oliset Enot including Litetime Drift	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±4	10	mV
QVO Error Including Lifetime Drift	V	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-14	-4 ±6	14	mV
QVO End including clietime Difft	V_{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



^[2] Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.
[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LMABTR-066B5

ACS37002LMABTR-066B5	Selection Identifier			
Parameter (Units)	Gain_Sel_1 (Boolean)	Max IP (A)		
Type	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	30	66.7
Selection	0	1	25	80
Combination	1	0	20	100
	1	1	15	133.3

 $\textbf{ACS37002LMABTR-066B5 PERFORMANCE CHARACTERISTICS:} \ \ \text{Valid through full operating temperature range,} \ \ T_{A} = -40^{\circ}\text{C} \ \ \text{to} \ \ 150^{\circ}\text{C},$ $C_{BVPASS} = 0.1 \mu F$, and $V_{CC} = 5 V$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE	*					
		Gain Sel 00	-66.7	_	66.7	А
Comment Committee Domes		Gain Sel 01	-80	-	80	А
Current Sensing Range	I _{PR}	Gain Sel 10	-100	-	100	А
		Gain Sel 11	-133.3	-	133.3	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	30	-	mV/A
Sensitivity	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	_	25	-	mV/A
Sensitivity	Selis	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	_	20	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	_	15	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	$V_{IOUT(Q)}$	Bidirectional; I _P = 0 A, T _A = 25°C	_	2.5	-	V
TOTAL ERROR ($V_{IOUT(ACTUAL)}$ – (Sens _{(IDE} AND TOTAL ERROR COMPONENTS	_{:AL)} × I _{PR} + V _{REF})) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 150°C or -40°C to 25°C	-1.5	-0.5 ±0.6	1.5	%
7 0 10 5	V_{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±3	10	mV
Zero Current Reference Error		$V_{REFactual} - V_{REFideal}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±3	10	mV
Offset Error		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	-1 ±4	8	mV
Oliset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
QVO Error	V	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±5	10	mV
QVO EIIOI	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT_LTD}	$I_P = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 150°C or -40°C to 25°C	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including	\/	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	$V_{REFactual} - V_{REFideal}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-2 ±3	10	mV
Offset Error Including Lifetime Drift	V	V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±5	10	mV
Onset End including Engline Difft	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±4	10	mV
OVO Frankladina Lifetima Drift		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



^[3] Lifetime drift characteristics are based on a statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LMABTR-050U5

ACS37002LMABTR-050U5 Gain, Sel Pin Performance Key

ACCOST 002EMIAD 114-03003 C		se itey		Ociection identifier
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	80	50
Selection	0	1	100	40
Combination	1	0	120	33.3
	1	1	60	66.7

ACS37002LMABTR-050U5 PERFORMANCE CHARACTERISTICS: Valid through full operating temperature range, T_A = -40°C to 150°C, $C_{PVPASS} = 0.1 \, \mu F$, and $V_{CC} = 5 \, V$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE						
		Gain Sel 00	0	_	50	А
Current Sensing Bangs		Gain Sel 01	0	_	40	А
Current Sensing Range	I _{PR}	Gain Sel 10	0	_	33.3	А
		Gain Sel 11	0	_	66.7	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	80	-	mV/A
Consider	Sama	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	100	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	120	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	_	60	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	25	50	100	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Unidirectional; I _P = 0 A, T _A = 25°C	-	0.5	-	V
TOTAL ERROR ($V_{IOUT(ACTUAL)}$ – (Sens _{(IDI} AND TOTAL ERROR COMPONENTS	EAL) × I _{PR} + V _{REF})) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	I _P = I _{PR(max)} , T _A = 25°C to 150°C or -40°C to 25°C	-1.5	-0.5 ±0.6	1.5	%
Z Ourset Defense - Emer	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
O#+ F		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	-1 ±4	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
0)/0 =		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	−3 ±5	10	mV
QVO Error	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT_LTD}	$I_{P} = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	I _P = I _{PR(max)} , T _A = 25°C to 150°C or –40°C to 25°C	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
05.5.1.1.1.15.1	.,	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-10	-2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = –40°C to 25°C	-10	±4	10	mV
010 5 1 1 1 1 1 1 1 1 1 1 1 1 1		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0 \text{ A}$, $T_A = -40^{\circ}\text{C}$ to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



^[2] Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LMABTR-066U5

ACS37002LMABTR-066U5 Gain, Sel Pin Performance Key

ACCOST OUZEWIAD I IN-000003 Co	COST 002EMABTIC-00003 Gain_Get in the florinance fixey				
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)	
Туре	Digital Input	Digital Input	Calculation	Bidirectional	
	0	0	60	66.7	
Selection	0	1	50	80	
Combination	1	0	40	100	
	1	1	30	133.3	

ACS37002LMABTR-066U5 PERFORMANCE CHARACTERISTICS: Valid through full operating temperature range, T_A = -40°C to 150°C, $C_{\text{BVDASS}} = 0.1 \,\mu\text{F}$, and $V_{\text{CC}} = 5 \,\text{V}$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE	'					
		Gain Sel 00	0	_	66.7	А
Comment Compliant Domes		Gain Sel 01	0	-	80	А
Current Sensing Range	I _{PR}	Gain Sel 10	0	-	100	А
		Gain Sel 11	0	-	133.3	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	60	-	mV/A
Camaitivity	Sama	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	50	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	_	40	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	_	30	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	25	50	100	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Unidirectional; I _P = 0 A, T _A = 25°C	-	0.5	-	V
TOTAL ERROR ($V_{IOUT(ACTUAL)}$ – (Sens _{(IDE} AND TOTAL ERROR COMPONENTS		/ (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 150°C or -40°C to 25°C	-1.5	-0.5 ±0.6	1.5	%
Zero Current Reference Error	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
O#		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	-1 ±4	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
0)/0 5	.,	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	−3 ±5	10	mV
QVO Error	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT_LTD}	$I_{P} = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	I _P = I _{PR(max)} , T _A = 25°C to 150°C or -40°C to 25°C	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
0	1,,	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-10	-2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±4	10	mV
	1	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



^[2] Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LMABTR-050B3

ACS37002LMABTR-050B3 Gain Sel Pin Performance Key

ACCOST 002EMIAD 114-030D3 C		ce itey		Ociection identifier
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	26.4	50
Selection	0	1	33	40
Combination	1	0	39.6	33.3
	1	1	19.8	66.7

ACS37002LMABTR-050B3 PERFORMANCE CHARACTERISTICS: Valid through full operating temperature range, T_A = -40°C to 150°C, $C_{PVDASS} = 0.1 \text{ uF}$, and $V_{CC} = 3.3 \text{ V}$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE	·					
		Gain Sel 00	-50	_	50	А
Comment Complian Domes		Gain Sel 01	-40	_	40	А
Current Sensing Range	I _{PR}	Gain Sel 10	-33.3	_	33.3	Α
		Gain Sel 11	-66.7	-	66.7	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	26.4	-	mV/A
Sonoitivity	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	33	-	mV/A
Sensitivity	Sells	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	39.6	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	-	19.8	_	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	$V_{IOUT(Q)}$	Bidirectional; I _P = 0 A, T _A = 25°C	-	1.65	-	V
TOTAL ERROR ($V_{IOUT(ACTUAL)}$ – (Sens _{(IDE} AND TOTAL ERROR COMPONENTS) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 150°C or -40°C to 25°C	-1.5	-0.5 ±0.6	1.5	%
7 O	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
O#+ F	.,	V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	−1 ±4	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
0\/0 F====		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	−3 ±5	10	mV
QVO Error	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]	'			
Total Error Including Lifetime Drift	E _{TOT_LTD}	$I_P = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	I _P = I _{PR(max)} , T _A = 25°C to 150°C or -40°C to 25°C	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
05.5.1.1.1.15.5.5.5	.,	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25^{\circ}$ C to 150°C	-10	-2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±4	10	mV
0.40 5 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	. ,	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	V _{IOUT(O)} , I _P = 0 A, T _A = -40°C to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



^[2] Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LMABTR-066B3

ACS37002LMABTR-066B3 Gain Sel Pin Performance Key

AC337 002EINIAD 1 IX-000D3 O	Ociection identifier			
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	19.8	66.7
Selection	0	1	16.5	80
Combination	1	0	13.2	100
	1	1	9.9	133.3

 $\textbf{ACS37002LMABTR-066B3 PERFORMANCE CHARACTERISTICS:} \ \ \text{Valid through full operating temperature range,} \ \ T_{A} = -40^{\circ}\text{C} \ \ \text{to} \ \ 150^{\circ}\text{C},$ $C_{BYPASS} = 0.1 \, \mu F$, and $V_{CC} = 3.3 \, V$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE	,					
		Gain Sel 00	-66.7	_	66.7	А
0 10 : 5		Gain Sel 01	-80	-	80	А
Current Sensing Range	I _{PR}	Gain Sel 10	-100	-	100	А
		Gain Sel 11	-133.3	-	133.3	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	19.8	_	mV/A
Compatibility.	0	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	_	16.5	_	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	13.2	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	-	9.9	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirectional; I _P = 0 A, T _A = 25°C	_	1.65	-	V
TOTAL ERROR ($V_{\rm IOUT(ACTUAL)}$ – (Sens _{(IDE} AND TOTAL ERROR COMPONENTS	(AL) × I _{PR} + V _{REF}) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_{P} = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 150°C or -40°C to 25°C	-1.5	-0.5 ±0.6	1.5	%
Zero Current Reference Error	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
Offset Error		$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-8	-1 ±4	8	mV
Oliset Elloi	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0 A$, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
QVO Error	\/	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-10	−3 ±5	10	mV
QVO EIIOI	V _{QE}	$V_{IOUT(Q)}$, $I_P = 0 A$, $T_A = -40^{\circ}C$ to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT_LTD}	$I_{P} = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	$I_P = I_{PR(max)}$, $T_A = 25$ °C to 150°C or -40°C to 25°C	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
Office Francisco Including 177.7		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±4	10	mV
OVO Formula distribution di Stationa Deife	.,,	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



¹²¹ Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LMABTR-050U3

CS37002LMABTR-050U3	337002LMABTR-050U3 Gain_Sel Pin Performance Key					
Parameter (Units)	Parameter (Units) Gain_Sel_1 (Boolean) Gain_Sel_0 (Boolean) Sens (mV/A)					
Туре	Digital Input	Digital Input	Calculation	Bidirectional		
	0	0	52.8	50		
Selection	0	1	66	40		
Combination	1	0	79.2	33.3		
	1	1	39.6	66.7		

 $\textbf{ACS37002LMABTR-050U3 PERFORMANCE CHARACTERISTICS:} \ \ \text{Valid through full operating temperature range, } \ T_{A} = -40^{\circ}\text{C} \ \text{to } 150^{\circ}\text{C},$ = 0.1 μ F, and V_{CC} = 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE						`
0 10 1		Gain Sel 00	0	_	50	А
		Gain Sel 01	0	_	40	А
Current Sensing Range	I _{PR}	Gain Sel 10	0	-	33.3	А
		Gain Sel 11	0	_	66.7	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	52.8	-	mV/A
Canaltivity	Cana	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	66	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	79.2	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	-	39.6	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	25	50	100	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Unidirectional; I _P = 0 A, T _A = 25°C	-	0.33	-	V
TOTAL ERROR (V _{IOUT(ACTUAL)} – (Sens _{(IDI} AND TOTAL ERROR COMPONENTS	EAL) × I _{PR} + V _{REF}))) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_{P} = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 150°C or -40°C to 25°C	-1.5	-0.5 ±0.6	1.5	%
7 0 10 5	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
O#	.,	V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	-1 ±4	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
0)/0 5		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	−3 ±5	10	mV
QVO Error	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	OMPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT LTD}	$I_{P} = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	$I_P = I_{PR(max)}, T_A = 25^{\circ}C \text{ to } 150^{\circ}C \text{ or } -40^{\circ}C \text{ to } 25^{\circ}C$	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-10	-2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	$V_{\text{IOUT(Q)}} - V_{\text{REF}}$, $I_{\text{P}} = 0$ A, $T_{\text{A}} = -40^{\circ}\text{C}$ to 25°C	-10	±4	10	mV
		$V_{\text{IOLIT(O)}}, I_{\text{P}} = 0 \text{ A}, T_{\text{A}} = 25^{\circ}\text{C to } 150^{\circ}\text{C}$	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	$V_{\text{IOUT(Q)}}$, $I_{\text{P}} = 0$ A, $T_{\text{A}} = -40$ °C to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



^[2] Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LMABTR-066U3

ACS37002I MARTR-066U3 Gain Sel Pin Performance Key

ACCOST 002ENIAD I IX-0000-	Gain_Sei Fili Feiloili	larice itey		Ociection identifier
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	39.6	66.7
Selection	0	1	33	80
Combination	1	0	26.4	100
	1	1	19.8	133.3

ACS37002LMABTR-066U3 PERFORMANCE CHARACTERISTICS: Valid through full operating temperature range, T_A = -40°C to 150°C, $C_{BVPASS} = 0.1 \,\mu\text{F}$, and $V_{CC} = 3.3 \,\text{V}$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE						
		Gain Sel 00	0	_	66.7	А
Current Sensing Denge		Gain Sel 01	0	-	80	А
Current Sensing Range	I _{PR}	Gain Sel 10	0	-	100	А
		Gain Sel 11	0	-	133.3	Α
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	39.6	-	mV/A
Sonoitivity	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	33	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	26.4	_	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	-	19.8	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	25	50	100	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Unidirectional; I _P = 0 A, T _A = 25°C	-	0.33	-	V
TOTAL ERROR ($V_{\rm IOUT(ACTUAL)}$ – (Sens _(IDE) AND TOTAL ERROR COMPONENTS	_{AL)} × I _{PR} + V _{REF})	/ (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25$ °C to 150°C or -40 °C to 25°C	-1.5	-0.5 ±0.6	1.5	%
Zero Current Reference Error	V _{RE}	$V_{REFactual} - V_{REFideal}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-10	-2 ±3	10	mV
Zero Guirent Reference Error		$V_{REFactual} - V_{REFideal}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±3	10	mV
Offset Error	.,	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-8	-1 ±4	8	mV
Oliset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
QVO Error		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±5	10	mV
QVO EIIOI	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	-1 ±4	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT LTD}	$I_P = I_{PR(max)}$	-3.6	-1.6 ±1.2	3.6	%
Sensitivity Error Including Lifetime Drift	E _{SENS_LTD}	I _P = I _{PR(max)} , T _A = 25°C to 150°C or –40°C to 25°C	-3.4	-1.5 ±1.1	3.4	%
Zero Current Reference Error Including	.,,	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
Offerst Francisco Including a Lifetime - Drift	.,,	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-10	-2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±4	10	mV
OVO Faranta de ale alia a Lifatina a Daiti		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±7	10	mV

^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.



¹²¹ Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002KMABTR-050B5

AACS37002KMARTR-050R5 Gain, Sel Pin Performance Key

AAC337002KWAB1K-030		Selection identifier		
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	40	50
Selection	0	1	50	40
Combination	1	0	60	33.3
	1	1	30	66.7

ACS37002KMABTR-050B5 PERFORMANCE CHARACTERISTICS: Valid through full operating temperature range, T_A = -40°C to 125°C, $C_{BVPASS} = 0.1 \mu F$, and $V_{CC} = 5 V$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE						
		Gain Sel 00	-50	_	50	А
O		Gain Sel 01	-40	-	40	А
Current Sensing Range	I _{PR}	Gain Sel 10	-33.3	-	33.3	А
		Gain Sel 11	-66.7	_	66.7	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	40	-	mV/A
Sensitivity	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	_	50	_	mV/A
Sensitivity	Seris	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	_	60	_	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	-	30	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirectional; I _P = 0 A, T _A = 25°C	-	2.5	-	V
TOTAL ERROR ($V_{\rm IOUT(ACTUAL)}$ – (Sens _{(IDE} AND TOTAL ERROR COMPONENTS	_(AL) × I _{PR} +V _{REF}))	/ (Sens _(IDEAL) × I _{PR})× 100				
Total Error	E _{TOT}	$I_{P} = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25^{\circ}C$ to 125°C, $T_A = -40^{\circ}C$ to 25°C	-1	-0.3 ±0.5	1	%
7 O	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 125°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
0" 15		$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 125°C	-8	±5	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	-1 ±3	8	mV
0)/0 5	V	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 125°C	-10	-3 ±4	10	mV
QVO Error	V _{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40^{\circ}$ C to 25°C	-10	±5	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT_LTD}	$I_P = I_{PR(max)}$	-3.4	-1.4 ±1.2	3.4	%
Sensitivity Error Including Lifetime Drift	E _{SENS LTD}	I _P = I _{PR(max)} , T _A = 25°C to 125°C or –40°C to 25°C	-3.2	-1.3 ±1.1	3.2	%
Zero Current Reference Error Including	_	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 125°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 125°C	-10	-2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40^{\circ}$ C to 25°C	-10	±4	10	mV
		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 125°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V _{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40^{\circ}$ C to 25°C	-10	±7	10	mV



^[1] Typicals values are the mean ±3 sigma of production distributions. These are formatted as mean ±3 sigma.
[2] Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002KMABTR-050B3

ACS37002KMARTR-050R3 Gain, Sel Pin Performance Key

ACCOTOCENIAD IN-COOL	ACCOTOCE TIME THE CHOMINANCE REY					
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)		
Туре	Digital Input	Digital Input	Calculation	Bidirectional		
	0	0	26.4	50		
Selection	0	1	33	40		
Combination	1	0	39.6	33.3		
	1	1	19.8	66.7		

ACS37002KMABTR-050B3 PERFORMANCE CHARACTERISTICS: Valid through full operating temperature range, T_A = -40°C to 125°C, $C_{PVDASS} = 0.1 \mu F$, and $V_{CC} = 3.3 \text{ V}$, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE				, ,,		
		Gain Sel 00	-50	_	50	Α
		Gain Sel 01	-40	_	40	Α
Current Sensing Range	I _{PR}	Gain Sel 10	-33.3	_	33.3	Α
		Gain Sel 11	-66.7	_	66.7	Α
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	26.4	-	mV/A
0		Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	_	33	_	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	39.6	_	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	-	19.8	_	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirectional; I _P = 0 A, T _A = 25°C	-	1.65	-	V
TOTAL ERROR (V _{IOUT(ACTUAL)} – (Sens _{(IDE} AND TOTAL ERROR COMPONENTS	_{AL)} × I _{PR} + V _{REF})) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	-0.5 ±0.6	1.75	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}$, $T_A = 25$ °C to 125°C, $T_A = -40$ °C to 25°C	-1	-0.3 ±0.5	1	%
7 0 10 5	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 125°C	-10	-2 ±3	10	mV
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-1 ±3	10	mV
0". 15		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 125°C	-8	±5	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}, I_P = 0 A, T_A = -40^{\circ}C \text{ to } 25^{\circ}C$	-8	-1 ±3	8	mV
0)/0 5		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 125°C	-10	-3 ±4	10	mV
QVO Error	V _{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40^{\circ}$ C to 25°C	-10	±5	10	mV
TOTAL ERROR AND TOTAL ERROR CO	MPONENTS IN	CLUDING LIFETIME DRIFT [2,3]				
Total Error Including Lifetime Drift	E _{TOT LTD}	$I_P = I_{PR(max)}$	-3.4	-1.4 ±1.2	3.4	%
Sensitivity Error Including Lifetime Drift	E _{SENS LTD}	I _P = I _{PR(max)} , T _A = 25°C to 125°C or –40°C to 25°C	-3.2	-1.3 ±1.1	3.2	%
Zero Current Reference Error Including		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 125°C	-10	-3 ±4	10	mV
Lifetime Drift	V _{RE_LTD}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	-2 ±3	10	mV
0	.,	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 125°C	-10	−2 ±5	10	mV
Offset Error Including Lifetime Drift	V _{OE_LTD}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±4	10	mV
OVO Former to alreading a Life-time a Duitt		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 125°C	-14	-4 ±6	14	mV
QVO Error Including Lifetime Drift	V_{QE_LTD}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40^{\circ}$ C to 25°C	-10	±7	10	mV

 $^{{\}tt [[1]]}$ Typicals values are the mean ± 3 sigma of production distributions. These are formatted as mean ± 3 sigma.



^[2] Typicals values are the mean ±3 sigma statistical combination of production and AEC-Q100 individual drift distributions. These are formatted as mean ±3 sigma.

^[3] Lifetime drift characteristics are based on a statistical combination of production distributions and worst case distribution of parametric drift of individuals observed during AEC-Q100 qualification. Contact Allegro MicroSystems for further information.

400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LLAATR-015B5

ACS37002LL AATR-015R5 Gain, Sel Pin Performance Key

AC33/002LLAATK-013D3	ACS37002LLAATR-019B9 Gain_Sei Pin Periormance Key					
Parameter (Units)	Gain_Sel_1 (Boolean)	an) Gain_Sel_0 (Boolean) Sens (mV/A)		Max IP (A)		
Туре	Digital Input	Digital Input	Calculation	Bidirectional		
	0	0	133.3	15		
Selection	0	1	166.6	12		
Combination	1	0	200	10		
	1	1	100	20		

 $\textbf{ACS37002LLAATR-015B5 PERFORMANCE CHARACTERISTICS:} \ \ \text{Valid through full operating temperature range,} \ \ T_A = -40 ^{\circ}\text{C} \ \ \text{to} \ \ 150 ^{\circ}\text{C},$ C_{BYPASS} = 0.1 $\mu\text{F},$ and V_{CC} = 5 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE						
		Gain Sel 00	-15	-	15	Α
Current Sensing Range		Gain Sel 01	-12	_	12	Α
Current Sensing Range	I _{PR}	Gain Sel 10	-10	-	10	Α
		Gain Sel 11	-20	-	20	Α
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	133.3	-	mV/A
Consistivity	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	166.6	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	200	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}		100	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirectional; I _P = 0 A, T _A = 25°C	-	2.5	-	V
TOTAL ERROR (V _{IOUT(ACTUAL)} – (Sens _{(I} AND TOTAL ERROR COMPONENTS	DEAL) × IPR + VREF) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_{P} = I_{PR(max)}$	-1.75	±1.4	1.75	%
Compilativity Forms		$I_{P} = I_{PR(max)}, T_{A} = 25^{\circ}C \text{ to } 150^{\circ}C$	-1.5	±1.3	1.5	%
Sensitivity Error	E _{SENS}	$I_P = I_{PR(max)}, T_A = -40^{\circ}C \text{ to } 25^{\circ}C$	-1.5	±1.2	1.5	%
Zana Carrant Dafanana - Faran		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	±4	10	mV
Zero Current Reference Error	V _{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	±5	10	mV
Offeet Freez		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	±4	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	±5	8	mV
QVO Error		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	±6	10	mV
QVO EIIOI	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±7	10	mV

 $[\]hbox{\small [1] Typicals are based on worse case mean ± 3 sigma values during production or production and qualification.}$



400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LLAATR-025B5

ACS37002LL AATR-025R5 Gain, Sel Pin Performance Key

AC337002LLAATR-023B3	Gain_Sei Fili Feriorii	ance Key		Selection identifier
Parameter (Units)	Gain_Sel_1 (Boolean)	ean) Gain_Sel_0 (Boolean) Sens (mV/A)		Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	80	25
Selection	0	1	66.6	30
Combination	1	0	53.3	37.5
	1	1	40	50

ACS37002LLAATR-025B5 PERFORMANCE CHARACTERISTICS: Valid through full operating temperature range, $T_A = -40^{\circ}\text{C}$ to 150°C, C_{BYPASS} = 0.1 μ F, and V_{CC} = 5 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE	•		·			`
		Gain Sel 00	-25	_	25	А
Current Consing Dance		Gain Sel 01	-30	-	30	Α
Current Sensing Range	I _{PR}	Gain Sel 10	-37.5	-	37.5	А
		Gain Sel 11	-50	-	50	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	_	80	-	mV/A
Committee in the control of the cont	0	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	_	66.6	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	_	53.3	-	mV/A
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	_	40	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirectional; I _P = 0 A, T _A = 25°C	-	2.5	-	V
TOTAL ERROR (V _{IOUT(ACTUAL)} – (Sens ₍ AND TOTAL ERROR COMPONENTS	DEAL) × IPR + VREF)) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_{P} = I_{PR(max)}$	-1.75	±1.4	1.75	%
	_	$I_{P} = I_{PR(max)}, T_{A} = 25^{\circ}C \text{ to } 150^{\circ}C$	-1.5	±1.3	1.5	%
Sensitivity Error	E _{SENS}	$I_{P} = I_{PR(max)}, T_{A} = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-1.5	±1.2	1.5	%
Zana Osamant Bafarrana Eman		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	±4	10	mV
Zero Current Reference Error	V _{RE}	$V_{REFactual} - V_{REFideal}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±5	10	mV
Offeet Freez	V	V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	±4	8	mV
Offset Error	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	±5	8	mV
0\/0.5	.,	V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	±6	10	mV
QVO Error	V _{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±7	10	mV

^[1] Typicals are based on worse case mean ±3 sigma values during production or production and qualification.



400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LLAATR-015B3

ACS37002LL AATR-015R3 Gain, Sel Pin Performance Key

AC337002LLAATK-013B3	Gain_Sei Fili Feiloilli	ance key		Selection identifier
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	88	15
Selection	0	1	110	12
Combination	1	0	132	10
	1	1	66	20

 $\textbf{ACS37002LLAATR-015B3 PERFORMANCE CHARACTERISTICS:} \ \ \text{Valid through full operating temperature range,} \ \ T_{A} = -40^{\circ}\text{C} \ \ \text{to} \ \ 150^{\circ}\text{C},$ C_{BYPASS} = 0.1 μ F, and V_{CC} = 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE	·					
Current Sensing Range		Gain Sel 00	-15	_	15	Α
		Gain Sel 01	-12	_	12	А
	I _{PR}	Gain Sel 10	-10	_	10	А
		Gain Sel 11	-20	_	20	А
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	_	88	-	mV/A
Canaltivity	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	_	110	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	_	132	-	·
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	_	66	_	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}	Typ. = factory-programmed default, FS = Full-Scale	50	100	200	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	$V_{IOUT(Q)}$ Bidirectional; $I_P = 0 \text{ A}$, $T_A = 25^{\circ}\text{C}$		2.5	-	V
TOTAL ERROR (V _{IOUT(ACTUAL)} – (Sens ₍	DEAL) × IPR + VREF)) / (Sens _(IDEAL) × I _{PR}) × 100	'			
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	±1.4	1.75	%
Sensitivity Error		$I_P = I_{PR(max)}, T_A = 25^{\circ}C \text{ to } 150^{\circ}C$	-1.5	±1.3	1.5	%
	E _{SENS}	$I_P = I_{PR(max)}, T_A = -40^{\circ}C \text{ to } 25^{\circ}C$	-1.5	±1.2	1.5	A A mV/A mV/A mV/A mV/A VFS V
Zero Current Reference Error		V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = 25°C to 150°C	-10	±4	10	mV
	V_{RE}	V _{REFactual} – V _{REFideal} , I _P = 0 A, T _A = –40°C to 25°C	-10	±5	10	mV
Offset Error		V _{IOUT(Q)} – V _{REF} , I _P = 0 A, T _A = 25°C to 150°C	-8	±4	8	mV
	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	±5	8	mV
0\/0 F====		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	±6	10	mV
QVO Error	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0 A$, $T_A = -40^{\circ}C$ to 25°C	-10	±7	10	mV

^[1] Typicals are based on worse case mean ±3 sigma values during production or production and qualification.



400 kHz, High Accuracy Current Sensor with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

ACS37002LLAATR-025U3

ACS37002LL AATP-025LI3 Gain, Sal Din Borformanco Kov

ACS77002LLAATR-02503 Gain_Set Pin Performance Key			Selection identifier	
Parameter (Units)	Gain_Sel_1 (Boolean)	Gain_Sel_0 (Boolean)	Sens (mV/A)	Max IP (A)
Туре	Digital Input	Digital Input	Calculation	Bidirectional
	0	0	105.6	25
Selection	0	1	88	30
Combination	1	0	70.4	37.5
	1	1	52.8	50

 $\textbf{ACS37002LLAATR-025U3 PERFORMANCE CHARACTERISTICS:} \ \ \text{Valid through full operating temperature range,} \ \ T_{A} = -40 ^{\circ}\text{C} \ \ \text{to} \ \ 150 ^{\circ}\text{C},$ C_{BYPASS} = 0.1 μ F, and V_{CC} = 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. [1]	Max.	Units
NOMINAL PERFORMANCE						`
		Gain Sel 00	-25	-	25	А
Current Canaina Danas		Gain Sel 01	-30	-	30	А
Current Sensing Range	I _{PR}	Gain Sel 10	-30	-	30	A A A A MV/A MV/A MV/A MV/A %FS V % % MV MV MV MV MV
		Gain Sel 11	-50	_	50	Α
		Gain Sel 00; I _{PR(min)} < I _P < I _{PR(max)}	-	105.6	_	mV/A
Consistivity	Sens	Gain Sel 01; I _{PR(min)} < I _P < I _{PR(max)}	-	88	-	mV/A
Sensitivity	Sens	Gain Sel 10; I _{PR(min)} < I _P < I _{PR(max)}	-	70.4	-	mV/A mV/A mV/A mV/A WFS V
		Gain Sel 11; I _{PR(min)} < I _P < I _{PR(max)}	_	52.8	-	mV/A
Overcurrent Fault Operating Range	I _{OCF-OR}			100	200	%FS
Zero Current Output Voltage	V _{IOUT(Q)}	V _{IOUT(Q)} Bidirectional; I _P = 0 A, T _A = 25°C		2.5	_	V
TOTAL ERROR ($V_{IOUT(ACTUAL)}$ – (Sens _{(I} AND TOTAL ERROR COMPONENTS	_{DEAL)} × I _{PR} + V _{REF})) / (Sens _(IDEAL) × I _{PR}) × 100				
Total Error	E _{TOT}	$I_P = I_{PR(max)}$	-1.75	±1.4	1.75	%
Sensitivity Error	_	$I_{P} = I_{PR(max)}, T_{A} = 25^{\circ}C \text{ to } 150^{\circ}C$	-1.5	±1.3	1.5	%
	E _{SENS}	$I_{P} = I_{PR(max)}, T_{A} = -40^{\circ}C \text{ to } 25^{\circ}C$	-1.5	±1.2	1.5	A A A A MV/A MV/A MV/A WFS V % % MV MV MV
Zero Current Reference Error			-10	±4	10	mV
	V _{RE}	$V_{REFactual} - V_{REFideal}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-10	±5	10	mV
Offset Error		$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = 25$ °C to 150°C	-8	±4	8	mV
	V _{OE}	$V_{IOUT(Q)} - V_{REF}$, $I_P = 0$ A, $T_A = -40$ °C to 25°C	-8	±5	8	mV
01/0 5		V _{IOUT(Q)} , I _P = 0 A, T _A = 25°C to 150°C	-10	±6	10	mV
QVO Error	V_{QE}	$V_{IOUT(Q)}$, $I_P = 0$ A, $T_A = -40^{\circ}$ C to 25°C	-10	±7	10	mV

^[1] Typicals are based on worse case mean ±3 sigma values during production or production and qualification.



with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

FUNCTIONAL DESCRIPTION

Power-On Reset Operation

The descriptions in this section assume: temperature = 25°C, with the labeled test conditions. The provided graphs in this section show V_{IOUT} moving with V_{CC} . The voltage of V_{IOUT} during a high-impedance state will be most consistent with a known load (R_{LOAD}, C_{LOAD}) .

POWER-ON

As V_{CC} ramps up, the ACS37002's V_{IOUT} and V_{REF} pins are high impedance until V_{CC} reaches and passes $V_{UVD(H)}$ [2] (or $V_{POR(H)}$ [1] if UVD is disabled). Once V_{CC} passes [2], the device takes some time without V_{CC} dropping below $V_{POR(L)}$ [8] before the device enters normal operation.

POWER-OFF

As V_{CC} drops below $V_{POR(L)}$ [8], the outputs will enter a high-impedance state. If UVD is enabled, before the device powers off, it will force V_{IOUT} to GND if $V_{CC} < V_{UVD(L)}$ [6] until $V_{POR(L)}$ [8] (seen in Figure 4 and Figure 6) is reached, at which point V_{IOUT} and V_{REF} will go high Z. If UVD is disabled, then V_{REF} and V_{IOUT} will continue to report until V_{CC} is less than $V_{POR(L)}$ [8] (seen in Figure 7), at which point they will go high Z.

Note: Since the device is entering a high Z state, and not driving the output, the time it takes the output to reach a steady state will depend on the external circuitry used.

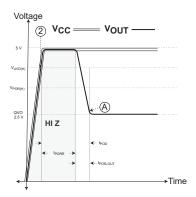


Figure 5: t_{POD} behavior UVD disabled, RL = Pull-Up POWER-ON RESET (POR)

If V_{CC} falls below $V_{POR(L)}$ [8] while in operation, the output will re-enter a high-impedance state. After V_{CC} recovers and exceeds $V_{UVD(H)}$ [2], the output will begin reporting again after the delay of t_{POD}

POWER-ON DELAY (T_{POD})

When the supply is ramped to $V_{UVD(H)}$ (seen in Figure 5 as [2]), the device will require a finite time to power its internal components before the outputs are released from high Z and can respond to an input magnetic field. Power-On Time, t_{POD} , is defined as the time it takes for the output voltage to settle within $\pm 10\%$ of its steady-state value under an applied magnetic field, which can be seen the time from [2] to [A]. After this delay, the output will quickly approach $V_{IOUT(IP)} = Sens \times I_P + V_{REF}$.

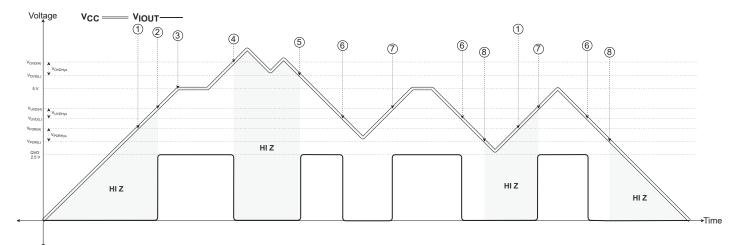


Figure 4: Power States Thresholds with V_{IOUT} Behavior for a 5 V Device, R_L = Pull-Down, UVD Enabled



Overvoltage and Undervoltage Detection (OVD/UVD)

To ensure that the device's output is reporting accurately, the device contains an overvoltage and an undervoltage detection flag. This flag on $V_{\rm IOUT}$ can be used to alert the system when the supply voltage for the device is outside of the operational range. UVD is only active on 5 V devices.

UNDERVOLTAGE DETECTION VOLTAGE THRESHOLDS (V_{UVD(H/L)})

The 5 V ACS37002 is factory-programmed with UVD enabled. It is important to note that when powering up the device for the first time after a POR event, V_{IOUT} and V_{REF} will remain high Z until V_{CC} is raised above $V_{UVD(H)}$ (seen in Figure 6 as [2]), at which point the V_{IOUT} and V_{REF} outputs will begin to normal operation.

If UVD is disabled or it is a 3.3 V device, V_{IOUT} and V_{REF} will begin report after V_{CC} raises above $V_{POR(H)}$ (seen in Figure 7 as [1]) under the same conditions.

If V_{CC} drops below $V_{UVD(L)}$ [6] after normal operation, V_{IOUT} will pull to GND regardless of R_{LOAD} configuration. The V_{IOUT} will remain at GND until V_{CC} raises above $V_{UVD(H)}$ [7] or V_{CC} falls below $V_{POR(L)}$ [8]. If V_{CC} rises above $V_{UVD(H)}$ [7] after a UVD, event, the V_{IOUT} and V_{REF} outputs will resume operation. If V_{CC} drops below $V_{POR(L)}$ [8], the device will enter a POR event and reset; V_{IOUT} and V_{REF} will switch to high Z if this occurs.

OVERVOLTAGE DETECTION VOLTAGE THRESHOLDS (V_{OVD(H/L)})

When V_{CC} raises above V_{OVD(H)} (seen in Figure 6 as [4]), the

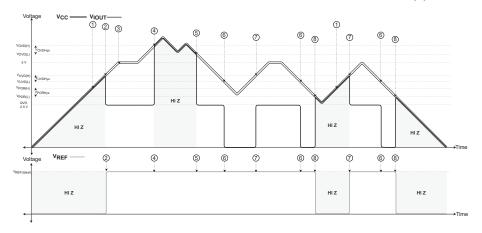


Figure 6: Power States Thresholds with V_{IOUT} and V_{REF} Behavior, 5 V Device, R_L = Pull-Up, UVD Enabled

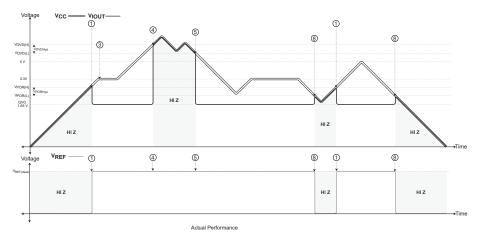


Figure 7: Power States Thresholds with V_{IOUT} and V_{REF} Behavior, 3.3 V Device, R_L = Pull-Up, UVD Disabled



output of the V_{REF} and V_{IOUT} pin will go high Z, V_{REF} be pulled to GND, and V_{IOUT} will be pulled to either VCC or GND, depending if R_{Load} is in a pull-up or pull-down configuration.

OVERVOLTAGE/UNDERVOLTAGE DETECTION HYSTERESIS (V_{OVD(HYS)}, V_{UVD(HYS)})

There is hysteresis between enable and disable thresholds to reducing nuisance flagging and clears. There is approximately 1 V and 0.4 V of hysteresis for Overvoltage and Undervoltage respectively. These can be seen represented in Figure 6 between the relevant thresholds.

OVERVOLTAGE AND UNDERVOLTAGE ENABLE AND DISABLE TIME $(T_{OVD(E/D)}, T_{UVD(E/D)})$

The enable time for OVD, $t_{\rm OVD(E)}$, is the time from $V_{\rm OVD(H)}$ [4] to OVD flag [B] in Figure 8. The UVD enable time, $t_{\rm UVD(E)}$, is the time from $V_{\rm UVD(L)}$ [6] to the UVD flag [D], also in Figure 8. The enable flag for both OVD and UVD has a counter to reduce transients faster than 64 μ s from triggering nuisance flags.

If V_{CC} ramps from $>V_{UVD(L)}$ [6] to $<V_{POR(L)}$ [8] (both seen in Figure 8) faster than $t_{UVD(E)}$, then the device will not have time to report a UVD event before power off occurs.

The disable time for OVD, $t_{\rm OVD(D)}$, is the time from $V_{\rm OVD(L)}$ [5] to the OVD clear to normal operation [C] in Figure 8. The UVD disable time, $t_{\rm UVD(D)}$, is the time from $V_{\rm UVD(H)}$ [7] to the point that the UVD flag clears and $V_{\rm IOUT}$ returns to nominal operation [E], also seen in Figure 8. The disable time does not have a counter for either UVD or UVD to release the output and resume reporting.

SUPPLY ZENER CLAMP VOLTAGES

If the voltage applied to the device continues to increase past overvoltage detection, there is a point when the Zener diodes will turn on. These internal diodes are in place to protect the device from short high voltage or ESD events and should \underline{NOT} be used as a feature to reduce the voltage on a line. Continued exposure to voltages higher than normal operating voltage, V_{CC} , can weaken or damage the Zener diodes, which will potentially damage the part.

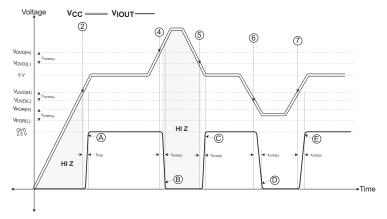


Figure 8: t_{POD} , $t_{OVD(E/D)}$, and $t_{UVD(E/D)}$ with R_L = Pull-Up



400 kHz, High Accuracy Current Sensor

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Absolute Maximum Ratings

These are the maximum application or environmental conditions that the device can be subjected before damage may occur.

FORWARD AND REVERSE SUPPLY VOLTAGE

These are the largest voltage magnitudes that can be supplied to V_{CC} from GND during programing or transient switching. This voltage should not be used as a DC voltage bias for an extended time.

FORWARD AND REVERSE OUTPUT VOLTAGE

The Forward Output Voltage or V_{FIOUT} voltage can be no greater than $V_{CC} + 0.5$ up to 6.5 V. This is the greatest voltage that the output can be biased with from GND during programming or transient switching. The Reverse Output Voltage or V_{RIOUT} should not drop below -0.5 V during programming or transient switching. These voltages should not be used as a DC voltage bias for an extended time.

FORWARD AND REVERSE REFERENCE/FAULT VOLTAGE

The Forward Reference/Fault Voltage or $V_{F\text{-}RF}$ voltage can be no greater than V_{CC} + 0.5 up to 6.5 V. This is the greatest voltage that the V_{REF} and V_{OCF} can be biased with from GND during

programming or transient switching. The Reverse Output Voltage or V_{R-RF} should not drop below -0.5~V during programming or transient switching. These voltages should not be used as a DC voltage bias for an extended time.

OUTPUT SOURCE AND SINK CURRENT

This is the maximum current that V_{IOUT} can passively sink or source before damage may occur.

AMBIENT TEMPERATURE (T₄)

This is the ambient temperature of the device. The Operating Ambient Temperature Range is the ambient temperature range that the Common Electricals and Common Performance Characteristics limits are valid. The Optimized Ambient Temperature Range is the ambient temperature range that the device-specific performance characteristics limits are valid. ACS37002L devices have optimized performance in the –40°C to 150°C ("L" temperature) range. ACS37002K devices have optimized performance in the –40°C to 125°C ("K" temperature) range. The –40°C to 125°C temperature performance optimized within the –40°C to 125°C temperature range but will still operate in the –40°C to 150°C ("L" temperature) range.



DEFINITIONS OF OPERATING AND PERFORMANCE CHARACTERISTICS

Zero Current Voltage Output (V_{IOUT(Q)}, QVO)

Zero Current Voltage Output or $V_{IOUT(Q)}$ (also called QVO) is defined as the voltage on the output, V_{IOUT} when zero amps are applied through I_P .

QVO Temperature Drift (VOF)

QVO Temperature Drift, or V_{QE} , is defined as the drift of QVO from room to hot or room to cold (25°C to 125/150°C or 25°C to -40°C respectively). To improve over temperature performance the temperature drift is compensated with Allegro's factory trim to remain within the limits across temperature.

Reference Voltage (V_{REF})

There is a Voltage Reference Output, (V_{REF}) on the ACS37002. This output reports the zero-current voltage for the output channel V_{IOUT} allowing for differential measurement and a device referred supply for the VOC pin.

Reference Voltage Temperature Drift (V_{RE})

Reference Voltage Temperature Drift, or V_{RE} , is defined as the drift of V_{REF} from room to hot or room to cold (25°C to 125/150°C or 25°C to -40°C respectively).

Offset Voltage (V_{OE})

Offset Voltage, or V_{OE} , is defined as the difference between QVO and V_{REF} (see Figure 9). V_{OE} includes the drift of QVO minus V_{REF} from room to hot or room to cold (25°C to 125/150°C or 25°C to -40°C respectively).

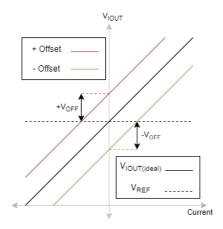


Figure 9: Offset (V_{OFF}) Between V_{IOUT} and V_{REF}

Output Saturation Voltage (V_{SAT(HIGH/LOW)})

Output Saturation Voltage, or V_{SAT} , is defined as the voltage that the V_{IOUT} does not pass as a result to an increasing magnitude of current. $V_{SAT(HIGH)}$ is the highest voltage the output can drive to while, $V_{SAT(LOW)}$ is the lowest. This can be seen in Figure 10. Note that changing the sensitivity does not change the V_{SAT} points.

OUTPUT VOLTAGE OPERATING RANGE (VOOR)

The Output Voltage Operating Range, or V_{OOR} , is the functional range for linear performance of V_{IOUT} and its related datasheet parameters. This can be seen in Figure 10. The V_{OOR} is the output region that the performance accuracy parameters are valid. It is possible for the output to report beyond these voltages until V_{SAT} , but certain parameters cannot be guaranteed. The output performance is demonstrated in Figure 10 through and beyond the V_{OOR} .

Voltage Output Operating Range for V _{CC} and Output Modes, V _{OOR(Vcc, Mode)}				
V _{CC} (V)	Bidrectional Unidirectional			
3.3	±1.32 +2.64			
5	5 ±2 +4			

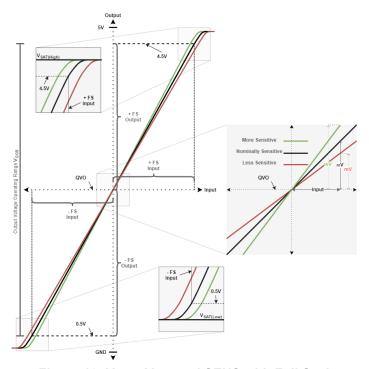


Figure 10: V_{OOR}, V_{SAT} and SENS with Full Scale

Sensitivity (Sens)

Sensitivity, or Sens, is the ratio of the output swing versus the applied current through the primary conductor, I_P . This current causes a voltage deviation away from QVO on the V_{IOUT} output until V_{SAT} . The magnitude and direction of the output voltage swing is proportional to the magnitude and direction of the applied current. This proportional relationship between output and input is Sensitivity and is defined as:

$$Sens = \frac{V_{\text{OUT(I1)}} - V_{\text{OUT(I2)}}}{I_1 - I_2}$$

where I_1 and I_2 are two different currents, and where $V_{IOUT(I1)}$ and $V_{IOUT(I2)}$ are the voltages of the device at the applied currents. V_{IOUT} , I_1 , or I_2 can be QVO with zero current.

Sensitivity Error (E_{sens})

Sensitivity Temperature Drift, or E_{sens} , is the drift of Sens from room to hot or room to cold (25°C to 125°C or 25°C to –40°C respectively). No trimming/programming is needed as temperature drift is compensated with Allegro's factory trim.

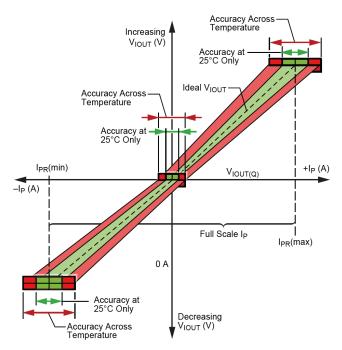


Figure 11: Output Accuracy Pocket for Room and Across Temperature

Gain Selection Pins

The ACS37002 features external gain selection pins that configures the device sensitivity. The gain select logic is latched based on the pin voltage at startup. Either pin may be shorted directly to VCC or GND, which is logic 1 or 0 respectively. Both pins include an internal 1 M Ω pull-down resistor to GND. Externally floating pins will be interpreted as logic 0; if both pins are floating, the device will be in the 00 configuration. Specific gain select performance can be found in the selection Performance Characteristics table. To change the gain of the device, refer to Figure 22 in the Application and Theory section.

Full Scale (FS)

Full Scale, or FS, is a method to relate an input and/or output to the max input and/or output of the device. For example, 50%FS of a 10A sensor is 5A, or 50% of its maximum input current. The 50% input of 5A will cause the output to move 50%, or 50%FS. FS is used to interchangeably refer to input and output deviations when discussing input steps, fault trip thresholds and relating input to output performance. FS_{INPUT} is the input bias that results in FS_{OUTPUT} and these two are directly related by the device actual sensitivity. Both FS can be seen in Figure 10, labeled as positive or negative FS input and FS output. The equation for input referred FS for a 5V bidirectional device is:

$$FS = V_{OOR(5V,Bi)}/Sens_{Actual} = \pm 2V/Sens_{Actual}$$

Note: that a percentage change in FS_{INPUT} is equivalent to a resultant percentage change of FS_{OUTPUT} and visa versa.

Nonlinearity (E_{I IN})

As the amount of field applied to the part changes, the sensitivity of the device can also change slightly. This is referred to as linearity error or E_{LIN} (see Figure 12). Consider two currents, $I_1(1/2 \text{ FS})$ and $I_2(FS)$. Ideally, the sensitivity of the device is the same for both fields. Linearity Error is calculated as the percent change in sensitivity from one field to another. Error is calculated separately for positive $(E_{LIN(+)})$ and negative $(E_{LIN(-)})$ currents, and the percent errors are defined as:

$$E_{LIN(\pm)} = \left(1 - \frac{Sens_{I2\pm}}{Sens_{I1\pm}}\right) * 100\%$$

where:

$$Sens_{Ix+} = (V_{IOUTIx+} - V_{REF}) / I_{x+}$$

and

$$Sens_{Ix-} = (V_{IOUTIx-} - V_{REF}) / I_{x-}$$

Ix are positive and negative currents through I_P , such that $|I_{+2}| = 2 \times |\ I_{+1}| \ and \ |\ I_{-2}| = 2 \times |\ I_{-1}|. \\ E_{LIN} = max(E_{LIN(+)}\ ,\ E_{LIN(-)})$



Total Output Error (E_{TOT})

The Total Output Error is the current measurement error from the sensor IC as a percentage of the actual applied current. This is equivalent to the difference between the ideal output voltage and the actual output voltage, divided by the ideal sensitivity, relative to the current applied to the device, or simplified to:

$$E_{TOT(\pm)} = \left(1 - \frac{V_{IOUT_Actual(\pm I)}}{V_{IOUT_Ideal(\pm I)}}\right) * 100\%$$

where

$$V_{IOUT\ Actual(I\pm)} = \pm I \times Sens_{Actual} + QVO_{Actual}$$

and

$$V_{IOUT\ Ideal(I\pm)} = \pm I \times Sens_{Ideal} + V_{REF\ Actual}$$

Total Output Error incorporates all sources of error and is a function of current. At relatively high currents, Total Output Error will be mostly due to sensitivity error, and at relatively low inputs, Total Output Error will be mostly due to Offset Voltage (V_{OE}). At I=0 A, Total Output Error approaches infinity due to the offset. An example of total error at FS can be seen in Figure 12.

Note: Total Output Error goes to infinity as the amount of applied field approaches 0 A.

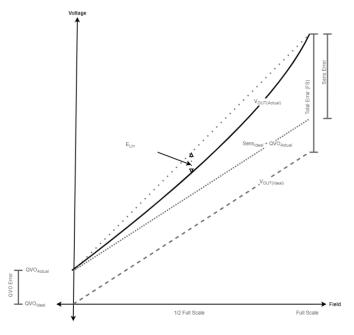


Figure 12: Accuracy Error

Power Supply Offset Error (V_{PS})

Power Supply Offset Error or V_{PS} is defined at the offset error in mV between V_{CC} and V_{CC} $\pm 10\%$ V_{CC} . For a 5 V device, this is 5 to 4.5 V and 5 to 5.5 V. For a 3.3 V device, this is 3.3 to 3 V and 3.3 to 3.6 V.

Offset Power Supply Rejection Ratio (PSRRO)

The Offset Power Supply Rejection Ratio or PSRRO is defined as $20 \times log$ of the ratio of the change of QVO in volts over a ± 100 mV variable AC V_{CC} centered at 5 V reported as dB in a specified frequency range. This is an AC version of the V_{PS} parameter. The equation is shown below:

$$PSRR_O = 20\log\left(\frac{\Delta QVO}{\Delta V_{CC}}\right)$$

Power Supply Sensitivity Error (E_{PS})

Power Supply Sensitivity Error, or E_{PS} , is defined as the percent sensitivity error measured between V_{CC} and $V_{CC} \pm 10\%$. For a 5 V device, this is 5 to 4.5 V and 5 to 5.5 V. For a 3.3 V device, this is 3.3 to 3 V and 3.3 to 3.6 V.

Sensitivity Power Supply Rejection Ratio (PSRRS)

The Sensitivity Power Supply Rejection Ratio or PSRRS is defined as 20 \times log of the ratio of the % change the sensitivity over the % change in V_{CC} (±100 mV variable AC V_{CC} centered at 5 V) reported as dB in a specified frequency range. This is the AC version of the E_{PS} parameter. The equation is shown below:

$$PSRR_S = 20 log \left(\frac{\Delta\%SENS}{\Delta\%V_{CC}} \right)$$

FAULT BEHAVIOR

Overcurrent Fault (OCF)

As the output swings, the Overcurrent Fault pin will trigger with an active low flag if the sensed current exceeds its comparator threshold. This is internally compared with either the factory-programmed thresholds or via the VOC voltage when $V_{\rm VOC}\!>\!0.1$ V. This flag trips symmetrically for the positive and negative OCF operating point.

The implementation for the OCF circuitry is accurate over temperature and does not require further temperature compensation as it is dependent on the Sens and $V_{\rm OFF}$ parameters that are factory-trimmed flat over temperature.

OVERCURRENT FAULT OPERATING RANGE/POINT (I_{OCF-OR}, I_{OCF-OP})

Overcurrent Fault Operating Range is the functional range that the OCF thresholds can be set in terms of percentage of full-scale output swing. The Overcurrent Fault Operating Point is the specific point at which the OCF trigger will occur, and is set by either $V_{\rm VOC}$ or the factory default setting. The $I_{\rm OCF-OP}$ can be seen in Figure 13 as [9] along with the FAULT pin functionality.

OVERCURRENT FAULT HYSTERESIS (IOCF-HYST)

Overcurrent Fault Hysteresis or $I_{OCF-HYST}$ is defined as the magnitude of percent FS that must drop before a fault assertion will be cleared. This can be seen as the separation between the voltages [9] to [10] in Figure 13. Note the MASK and HOLD functionality are independent of each other. The ACS37002 comes standard with an OCF_{HYS} of 120 mV (on the output) or 6%FS for a 5 V device and 9%FS for a 3.3 V device.

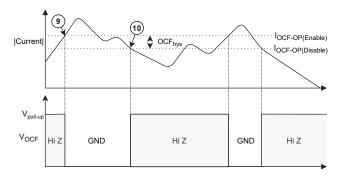


Figure 13: Fault Thresholds and OCF Pin Functionality

VOLTAGE OVERCURRENT PIN (VOC)

The fault trip points can be set using the VOC pin as the direct analog input for the fault trip point. The VOC pin voltage can be set using resistor dividers from V_{REF} on bidirectional devices. The fault performance is valid when V_{VOC} is within the VOC Operating Voltage Range or <0.1 V. The device will respond to voltage outside of the defined valid performance region with varied results. For a 5 V bidirectional device, setting the VOC pin to 0.5 V selects the minimum trip point, $I_{FAULT(min)}$, and setting the pin to 2 V selects the maximum trip point, $I_{FAULT(max)}$ as defined by selection performance tables. All voltages between 0.5 to 2 V for 5 V option and 0.33 to 1.321 V for 3.3 V option can linearly select a trip point between the minimum and maximum levels, as shown in Figure 14. When V_{OC} < 0.1 V, the internal EEPROM fault level will be used.

The resulting equation for the fault is:

$$OCF_{\%FS}$$
 [%] = $\frac{V_{OC(V_{CC})}[V]}{V_{OC(V_{CC})100\%}[V]} \times 100$ [%]

$$I_{\text{OCF}}[A] = OCF_{\text{\%FS}}[\%] \times I_{PR}[A]$$

Table 1: V_{OC(Vcc)} thresholds and corresponding percentage of the Full-Scale Output for Bidirectional and Unidirectional operational modes

•		•		
V 00	V 00	Fault Operation Point %FS		
V _{OC(3.3V)} (V)	V _{OC(5V)} (V)	Bidirectional	Unidirectional	
<0.1		100% (factory default)	50% (factory default)	
0.330	0.5	50%	25%	
0.466	0.75	75%	37.5%	
0.661	1	100%	50%	
0.826	1.25	125%	62.5%	
0.991	1.5	150%	75%	
1.156	1.75	175%	85%	
1.321	2	200%	100%	

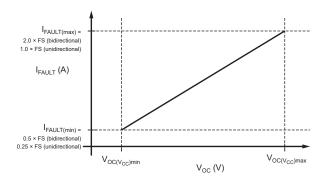


Figure 14: VOC Functional Range



OVERCURRENT FAULT ERROR (E_{OCF})

Fault Error or $E_{\rm OCF}$ is the error between the $I_{\rm OCF\text{-}OP(actual)}$ and $I_{\rm OCF\text{-}OP(ideal)}$.

OVERCURRENT FAULT RESPONSE TIME (TOCE)

Overcurrent Response Time or t_{OCF} is defined as the time from the input reaches the operating point [9] (seen in Figure 15) until the OCF pin falls below $V_{FAULT\text{-}ON}$ [G]. If the OCF Mask is disabled, then t_{OCF} is equal to $t_{OCF\text{-}R}$ seen as the time from [9] until [F].

OVERCURRENT FAULT REACTION TIME (TOCE-R)

Overcurrent Reaction Time or t_{OCF-R} is defined as the time from the current input rising above I_{OCF-OP} at point [9] in Figure 15 until the OCF pin reaches V_{OCF-ON} at point [F] with the OCF mask disable. This is the time required for the device to recognize and clear the fault, seen as the time between [10] until [I].

OVERCURRENT FAULT MASK TIME (T_{OCF-MASK})

Overcurrent Fault Mask Time or $t_{OCF\text{-}MASK}$ is defined as the additional amount of time the OCF must be present beyond the $t_{OCF\text{-}R}$ time (seen in Figure 15 [F] until [G]). This is to reduce nuisance tripping of the FAULT pin. If an OCF occurs, but does not persist beyond $t_{OCF\text{-}R} + t_{OCF\text{-}MASK}$, it is not reported by the device (seen in Figure 16). This prevents short transient spikes from causing erroneous OCF flagging. Factory default setting is $t_{OCF\text{-}MASK} = 0~\mu s$.

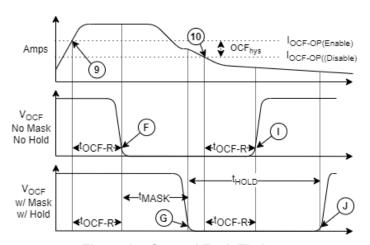


Figure 15: General Fault Timing.

Note: the MASK and HOLD functionality are independent of each other

OVERCURRENT FAULT HOLD TIME (T_{OCF-HOLD})

Overcurrent Fault Hold Time or t_{OCF-HOLD} is defined as the minimum time OCF flag will be asserted after a sufficient OCF event. After the hold time has been reached, the OCF will release if the OCF condition has ended (seen in Figure 15 [G] until [J]) or persist if the OCF condition is still present (seen in Figure 17 [G] until [J]). Factory default is 0 ms.

OVERCURRENT FAULT PERSIST

The ACS37002 has a fault persist option that will maintain the OCF flag if a flag occurred until a POR event.

OCF DISABLE

The ACS37002 has the ability to disable overcurrent fault functionality; when this is disabled, the OCF pin will remain in high Z.

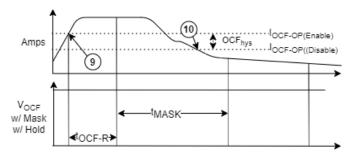


Figure 16: Fault Condition Clearing Before Mask Time Is Reached

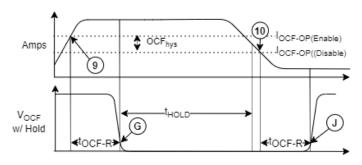


Figure 17: Fault Hold with Clear Fault After Hold Time

DYNAMIC RESPONSE PARAMETERS

The descriptions in this section assume: temperature =25°C, and output loads are within limits on Common Electrical table. The step applied is a input step that corresponds to 1 V deviation on the output, unless otherwise stated.

Propagation Time (t_{pd})

The time interval between a) when the sensed current reaches 10% of its stable value, and b) when the sensor output reaches 10% of its stable value for a step input. See Figure 18.

Rise Time (t_R)

The time interval between a) when the sensor reaches 10% of its stable value, and b) when it reaches 90% of the stable value for a step input. See Figure 18.

Response Time (t_{RESPONSE})

The time interval between a) when the sensed current reaches 90% of its stable value, and b) when the sensor output reaches 90% of its stable value. See Figure 18.

Overshoot

The amount, in percent of step size, the output voltage (V_{IOUT}) rises past the steady state output voltage. see Figure 19.

Settling Time

The amount of time it takes for the output voltage (V_{IOUT}) to settle to between \pm 3% of the steady state output. see Figure 19.

Temperature Compensation

To help compensate for the effects temperature has on performance, the ACS37002 has an integrated internal temperature sensor. This sensor and compensation algorithms help to standardize device performance over the full range of optimized temperatures. This allows for room temperature system calibration and validation of end-of-line modules.

Temperature Compensation Update Rate

There is an 8 ms update time that is required to maintain a valid temperature compensated output; that is, temperature compensations are calculated and applied every 8 ms.

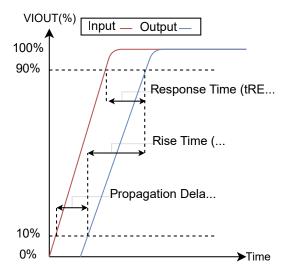


Figure 18: Dynamic Response Parameters

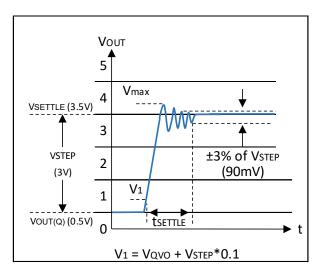


Figure 19: Overshoot and Settling Time (3 V step shown)



APPLICATION AND THEORY

Application Circuits

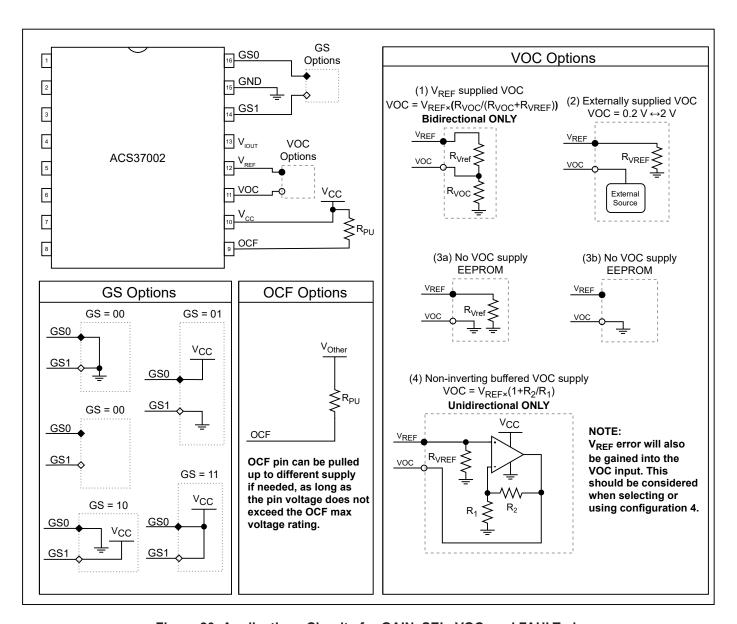


Figure 20: Applications Circuits for GAIN_SEL, VOC, and FAULT pin

These configurations are simplified to the network required for functionality.

Bypass and load capacitors are recommend for best performance.



Theory and Functionality – VOC and OCF

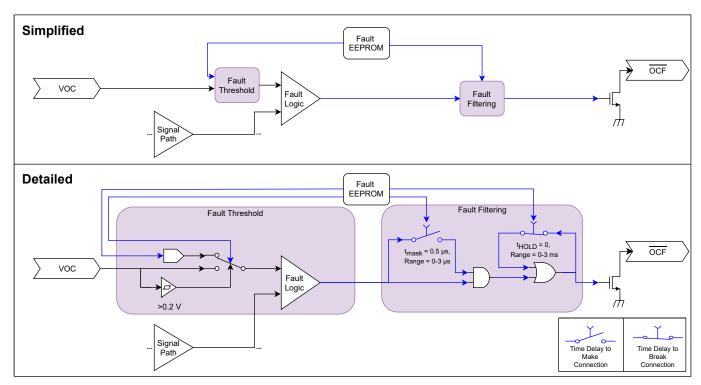


Figure 21: OCF Signal Path Simplified and Detailed Blocks of Functionality

VOC DRIVEN BY NON-INVERTING BUFFERED VREF

If the VOC pin is being driven by a non-inverted buffered V_{REF} , it is important to consider that any error from the V_{REF} pin will be gained as well. For instance, if V_{REF} error is +10 mV and the gain = 4 for the non-inverting operational amplifier, then the VOC pin will be 40 mV from the expected target. For unidirectional devices, OCF would be subjected to an additional 4% error due to the error propagation from V_{REF} through the gain stage.

POWER SUPPLY DECOUPLING CAPACITOR AND OUTPUT CAPACITIVE LOADS

The higher the capacitive load on the outputs (V_{REF} , V_{IOUT}), the larger the decoupling capacitor should be on the power supply (V_{CC}) to maintain performance.

C _{LOAD}	C _{BYPASS}
0 nF	>100 nF
1 nF	>100 nF
3 nF	>1 µF
6 nF	>10 µF

400 kHz, High Accuracy Current Sensor

with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

Dynamically Change Gain in a System

The ACS37002 has GAIN_SEL pins that are used to change the gain of the device on startup. If a more dynamic gain is desired, then reduce V_{CC} below $V_{POR(L)}$ and restart the device by returning V_{CC} to the nominal voltage with the new desired GAIN_SEL configuration. The GAIN_SEL pin voltage must greater than the

desired configuration voltage ($V_{H(SEL)}$) or $V_{L(SEL)}$) at or before $V_{CC} > V_{POR(H)}$ in order to successfully change the device gain. The GAIN_SEL pin voltage is latched at startup, and any changes to the pin voltages after the devices V_{IOUT} comes out of high Z will not affect gain. The cycle time to complete this operation is up to $2 \times t_{POD}$.

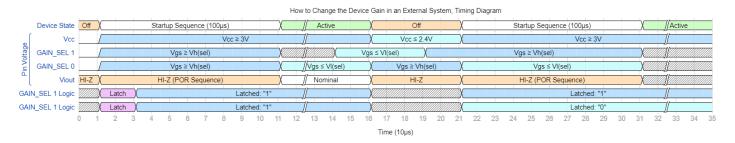


Figure 22: GAIN_SEL Dynamic Gain Changing Timing Diagram



with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

THERMAL PERFORMANCE

Thermal Rise vs. Primary Current

Self-heating due to the flow of current should be considered during the design of any current sensing system. The sensor, printed circuit board (PCB), and contacts to the PCB will generate heat as current moves through the system.

The thermal response is highly dependent on PCB layout, copper thickness, cooling techniques, and the profile of the injected current. The current profile includes peak current, current "on-time", and duty cycle. While the data presented in this section was collected with direct current (DC), these numbers may be used to approximate thermal response for both AC signals and current pulses.

The plot in Figure 23 shows the measured rise in steady-state die temperature of the ACS37002 versus continuous current at an ambient temperature, T_A , of 25 °C. The thermal offset curves may be directly applied to other values of T_A . Conversely, Figure 24 shows the maximum continuous current at a given T_A . Surges beyond the maximum current listed in Figure 25 are allowed given the maximum junction temperature, $T_{J(MAX)}$ (165°C), is not exceeded.

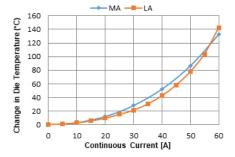


Figure 23: Self heating in the MA and LA package due to current flow

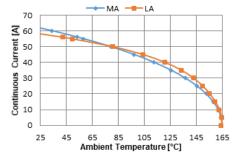


Figure 24: Maximum Continuous Current at a Given T_A

The thermal capacity of the ACS37002 should be verified by the end user in the application's specific conditions. The maximum junction temperature, $T_{J(MAX)}$ (165°C), should not be exceeded. Further information on this application testing is available in the DC and Transient Current Capability application note on the Allegro website.

Evaluation Board Layout

Thermal data shown in Figure 23 and Figure 24 was collected using the ASEK37002 Evaluation Board (TED-0002825). This board includes 750 mm² of 4 oz. copper (0.1388 mm) connected to pins 1 through 4, and to pins 5 through 8, with thermal vias connecting the layers. Top and bottom layers of the PCB are shown below in Figure 25.

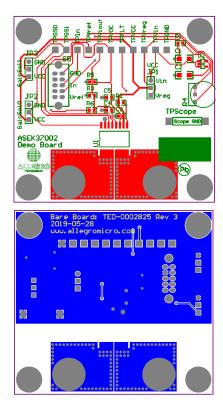


Figure 25: Top and Bottom Layers for ASEK37002
Evaluation Board

Gerber files for the ASEK37002 evaluation board are available for download from the Allegro website. See the technical documents section of the ACS37002 webpage.



PACKAGE OUTLINE DRAWINGS

For Reference Only – Not for Tooling Use (Reference MS-013AA)

NOT TO SCALE Dimensions in millimeters

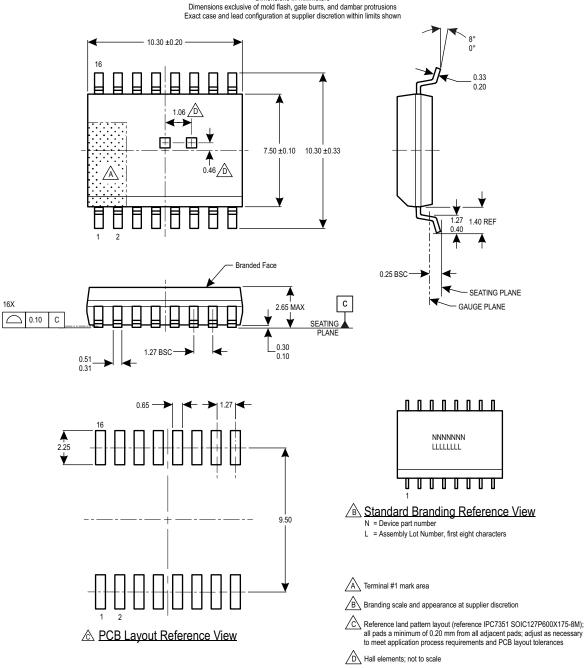


Figure 26: Package MA, 16-Pin SOICW

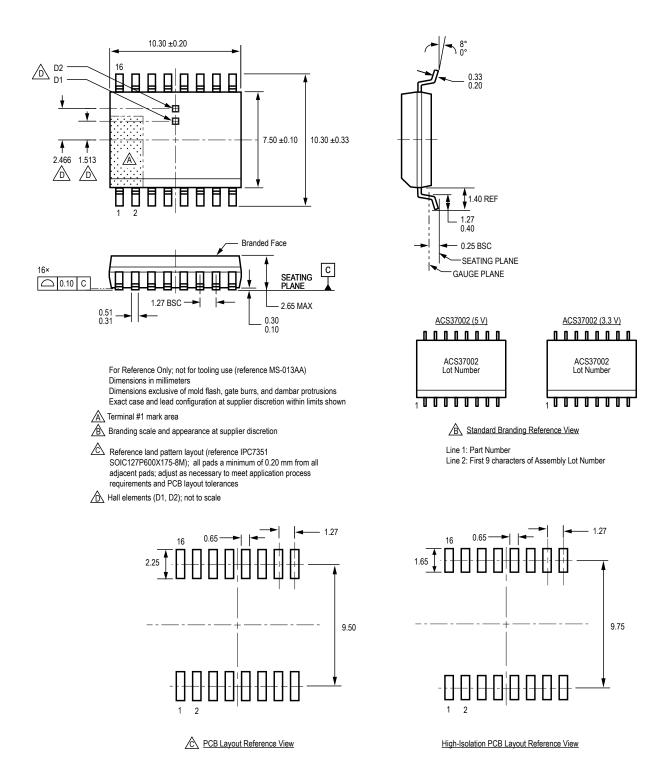


Figure 27: Package LA, 16-PIN SOICW



400 kHz, High Accuracy Current Sensor

with Pin-Selectable Gains and Adjustable Overcurrent Fast Fault in SOICW-16 Package

Revision History

Number	Date	Description
_	June 24, 2020	Initial release
1	July 8, 2020	Updated Features and Benefits, Selection Guide (page 2), Working Voltage values (page 4), Footnote 2 (pages 10-19), Voltage Overcurrent Pin section (page 30), and Branding (page 38)
2	October 16, 2020	Updated Features and Benefits, Description, and Figure 1 (page 1); added UL certification (page 2); updated Selection Guide table (page 2), Forward Output Voltage and Reverse Output Voltage symbols (page 3), Isolation Characteristics and MA Package Specific Performance tables (page 4), Supply Voltage, Supply Bypass Capacitor, Primary Conductor Resistance, Power-On Reset Voltage, Power-On Time, Undervoltage and Undervoltage Detection Threshold (page 7), Rise Time, Response Time, Propagation Delay Time, Noise Density (page 8), VOC Operating Voltage Range, OCF Reaction Time, OCF Mask, OCF Response Time (page 9); added footnote 4 (page 9); Performance Characteristic tables (pages 10-19); updated Current Sensing Range and Sensitivity values (pages 21-23); added Functional Description (pages 24-27), Definitions of Operating and Performance Characteristics (pages 28-32); updated Figure 20 (page 34), Theory and Functionality (pages 35-36).

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