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MOTOR CONTROL

Bluetooth Robot Car Controller



This wireless robot car controller board is built using an ESP32 BT/Wi-Fi module, 2 x H-Bridges, 3.3V regulator. It also includes an ESP32 programming connector, power LED, screw terminal connector for the power supply, header connector for motors, and high-value capacitors on the DC supply for smooth motor operations. The operating power supply is 8V to 24V DC. The project has two H-brides and each can drive 2.5A continues. The board is suitable for small and medium-sized robot cars. It is an open-source hardware project that can be programmed as per requirement. ESP32 I/O details are available in descriptions. ESP32 supports Bluetooth connectivity and the robot car can be controlled using a small phone, Laptop, or Tablet. The project was built using an ESP32-Wroom processor and this chip supports Bluetooth and Wi-Fi connectivity.

The project can be tested with example Arduino code which is provided below. The user will be able to drive a robot car with a PS3 Bluetooth remote. Refer to the link below to learn more about PS3 and ESP32 pairing, and ESP32 programming under Arduino IDE.

https://dronebotworkshop.com/ps3-esp32/

FEATURES

- Power Supply 8V to 24V DC
- Motor Load d up to 2.5A, Peak 6Amps Each Motor
- Over Current Shutdown Threshold 8Amps
- No Heatsink for H-Bridge
- PWM Frequency Up to 20Khz (Tested), ESP32 Default Output 500Hz
- Board Power LED
- Overtemperature Shut down with Latch Behaviour, H-Bridge
- _ Short Circuit Shut Down with Latch Behaviour, H-Bridge
- _ Chopper Current Limitation, H-Bridge
- VDD Undervoltage Shutdown
- 4 X 3MM Mounting Holes
- PCB Dimensions 48.90 X 41.28MM





ESP32 PINS VS H-BRIDGE U2 AND U3 PINS

- GPIO23/D23-PWM = U2 PWM, Motor 1
- GPIO22/D22-PWM = U3 PWM, Motor 2
- GPIO19/D19-DR = U2 Direction Control High or Low, Motor 1
- GPI017/D17-DR = U3 Direction Control High or Low, Motor 2
- GPIO16/D16 = Motor2 Enable/Disable (Solder Jumper J1 = Enable), DE-solder Jumper J1 for ESP32 Enable/Disable Control
- GPIO18/D18 = Motor1 Enable/Disable (Solder Jumper J2 = Enable), DE-solder Jumper J1 for ESP32 Enable/Disable Control

Schematic



Connections



Connections:

- CN1: Pin 1 VDD 8V to 24V, Pin 2 = GND
- CN2: Pin 1 & 2 = Motor 1, Pin 3 & 4 = Motor 1
- CN3: Pin 1 = 3.3V, Pin 2 = GND, Pin 3 = TX, Pin 4 = RX, Pin 5 = GPIOO, Pin 6 = Enable (Programming Connector)
- CN4: Pin 1 & 2 = Motor 2, Pin 3 & 4 = Motor 2
- J1: Jumper Closed (Pull Low) = Enable, can be controlled using ESP32 Pin GPIO16 Pin High = Disables Motor 1
- J1: Jumper Closed (Pull Low) = Enable, can be controlled using ESP32 Pin GPIO18 Pin High = Disables Motor 2
- D1: Power LED
- U4: 3.3V Regulator, Provides 3.3V to ESP32 processor input from Motor Supply 8V to 24V
- U3: H-Bridge Motor Driver, Motor 2







SILK SCREEN TOP



PCB DIMENSIONS 48.90 X 41.28MM



TOP LAYER

Parts List

BOM							
NO.	QNTY.	REF.	DESC.	MANUFACTURER	SUPPLIER	SUPPLIER PART NO	
1	1	CN1	2 PIN SCREW TERMINAL PITCH 5.08MM	PHOENIX	DIGIKEY	277-1247-ND	
2	2	CN2,CN4	4 PIN MALE HEADER PITCH 2,54MM	WURTH	DIGIKEY	732-5317-ND	
3	1	CN3	6 PIN MALE HEADER PITCH 2.65MM	WURTH	DIGIKEY	732-5319-ND	
4	2	C1,C9	10uF/10V CERAMIC SMD SIZE 0805	YAGEO/MURATA	DIGIKEY		
5	4	C2,C4,C7,C8	100nF/50V CERAMIC SMD SIZE 0805	YAGEO/MURATA	DIGIKEY		
6	1	C3	220uF/50V ELECTROLYTIC	NICHICON	DIGIKEY	493-2228-1-ND	
7	4	C5,C6,C10,C11	10nF/50V CERAMIC SMD SIZE 0805	YAGEO/MURATA	DIGIKEY		
8	1	D1	LED RED SMD SIZE 0805	OSRAM	DIGIKEY	475-1278-1-ND	
9	2	J1,J2	JUMPER- PCB SOLDER				
10	2	R1,R4	4.7K 5% SMD SIZE 0805	YAGEO/MURATA	DIGIKEY		
11	1	R2	1K 5% SMD SIZE 0805	YAGEO/MURATA	DIGIKEY		
12	1	R3	10K 5% SMD SIZE 0805	YAGEO/MURATA	DIGIKEY		
13	1	U1	ESP32-WROOM	ESP	DIGIKEY	1965-ESP32-WROOM-32E-N4TR-ND	
14	2	U2,U3	IFX9201	INFINEON	DIGIKEY	IFX9201SGAUMA1CT-ND	
15	1	U4	MP-K78L03-500R3	MORNSUM	DIGIKEY	2725-K78L03-500R3-ND	

Notes

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Android	Арр
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Android App	launched has 100k+
downloads - 4.5 stars.	rated with
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from ideas to boards

